

APPENDIX - C(1)

The algorithm of back propagation training method discussed in Section 3.4 is as follows :

Back-Propagation Training Algorithm (BPTA)

Back - propagation training rule contains training set H as follows :

$$H = \left\{ \left(\underline{x}_p, \underline{d}_p \right) ; p = 1, 2, \dots, P \right\}$$

where \underline{x}_p is $(n \times 1)$, \underline{d}_p is $(R \times 1)$. Note that n-th component of \underline{x}_p is of value -1. Hidden layer of size J-1 having output \underline{o} is selected. Note that J-th component of \underline{o} is of value -1 and \underline{y} , final output vector is $(R \times 1)$.

Now, major steps involved in BPTA as follows :

Step 1 Select initial weights w and v are initialized at small random values. Here w is $(R \times J)$, v is $(J \times n)$. Set $\eta > 0$ and initialize E_{\max} to small value (where E_{\max} is prespecified small error quantity). Counter(k) and error(E) are initialized.

$$k \leftarrow 1, \quad p \leftarrow 1, \quad E \leftarrow 0$$

Step 2 Choose any input vector \underline{x}_p and layer's output is computed

$$\underline{x} \leftarrow \underline{x}_p, \underline{d} \leftarrow \underline{d}_p$$

$$o_j \leftarrow f(\underline{v}_j' \underline{x}), \quad \text{for } j = 1, 2, \dots, J$$

where \underline{v}_j , a column vector, is the j-th row of v , and

$$y_r \leftarrow f(\underline{w}_r' \underline{o}) \quad \text{for } r = 1, 2, \dots, R$$

where \underline{w}_r , is column vector, is the r-th row of w .

Step 3 Compute error value E as

$$E \leftarrow \frac{1}{2} (d_r - y_r)^2 + E, \quad \text{for } r = 1, 2, \dots, R$$

Step 4 Output layer weights are adjusted :

$$w_{rj} \leftarrow w_{rj} + \frac{1}{2} \eta (d_r - y_r) (1 - y_r^2) o_j$$

for $r = 1, 2, \dots, R$
 $j = 1, 2, \dots, J$

Step 5 Hidden layer weights are adjusted :

$$v_{ji} \leftarrow v_{ji} + \frac{1}{4} \eta (1 - o_j^2) \sum_{r=1}^R (d_r - y_r) (1 - y_r^2) w_{rj} x_i$$

for $r = 1, 2, \dots, R$
 $j = 1, 2, \dots, J$
 $i = 1, 2, \dots, P.$

Step 6 If $p < P$ then $p \leftarrow p + 1$, $q \leftarrow q + 1$ and go to step 2; otherwise goto step 7.

Step 7 If $E < E_{\max}$, then stop the iterative procedure. Otherwise initialize error E to zero and enter the new training cycle by going to step 2.

Note: Where $f(\cdot)$ is activation function as follows:

$$f(x) = \frac{2}{1 + \exp(-\lambda x)} - 1,$$

with $\lambda=1$ and

$$f'(x) = \frac{1}{2} (1 - f(x) * f(x)).$$

APPENDIX C(2)

Back-Prop : This software package can be used for training multilayer feed forward ANNs and the training procedure used here discussed in Section 3.4.

```
/* Back-prop */

/* Back_pro.c for Multilayer Feedforward ANN */

#include <stdio.h>
#include <math.h>
#include <stdlib.h>
#include <conio.h>
#include <time.h>
#include <dos.h>

void main()
{
    float z[12][12],d[12][12],w[12][12],v[12][12],z1[12],d1[12];
    float e; int ip,r1,p,i,j,k,I,J,K,P,q; float m[12],n[12];
    float ed[12],ds[12];float dsl,s,ita,emax; int cnt,r,qmax,t1,t,t2;
    double y[12],o[12];
    char c;

    FILE *fp1,*fp2,*fp3,*fp5;

    clrscr(); gotoxy(3,7);
    printf( "\t This softwre needs three Data files:\n ");
    printf("\n\ti) INPUT.dat : Input data file containing P set of input ");
    printf("\n
                vectors each of dim I. \n");
    printf( "\n\tii) D OUT.dat : File containing K dim vector of Target ");
    printf("values.\n");
    printf( "\n\tiii) Test.dat : File containing I dim vector of Test val.");

    fp1= fopen("SR.DAT","r");
    fp2= fopen("SRD.DAT","r");
    fp3= fopen("TEST.DAT","r");
    fp5= fopen("SRN.DAT","w");

    if(fp1==NULL)
    {
        printf("\n Error open file-1");
        exit(0);
    }
}
```

```

    if(fp2==NULL)
    {
        printf("\nError open file-2");
        exit(0);
    }

    if(fp3==NULL)
    {
        printf("\nError open file-3");
        exit(0);
    }

    /* enter the data....*/
    printf( "\n\n Enter values of : ");
    printf("\n I= No. of Input neurons, K= Target val ");
    printf(" P= No of Patterns\n\t");
    scanf("%d",&I);
    printf("\t\t\n");
    scanf("%d",&K);
    printf("\t\t");
    scanf("%d",&P);
    printf("\n The val of I,K,P are =%d %d %d",I,K,P);
    I=I+1; /* for fixed Input = -1. */

printf("\n Reading the values of z[][] and d[][]\n");

for (p=1;p<=P;p++)
{
    for(i=1;i<=I-1;i++)

        fscanf(fp1,"%f",&z[p][i]);
        z[p][I] =-1;
    }
    for (p=1;p<=P;p++)
        for(k=1;k<=K;k++)
            fscanf(fp2,"%f",&d[p][k]);

    /* Enter no.of neurons in the hidden layer */
    clrscr();
    gotoxy(3,15);
    c= ' ';

do
{
    printf("Enter No.of neurons in Hidden Layer J   =:   ");
    scanf("%d",&J);
    printf("\t\t\t Learning const   = :\t");
    scanf("%f",&ita);
    printf("\t\t\t Max. Error   = :\t");
    scanf("%f",&emax);
    printf("\t\t\t No. of Iterations = :\t");
    scanf("%d",&qmax);
    J= J+1; /* For fixed hidden neuron = -1. */
}

```

```

/* generate w[] and v[] */

    randomize();
for(k=1;k<=K;k++)
for(j=1;j<=J;j++)
    w[k][j]= 2.0*((float)rand()/RAND_MAX)-1.0;

    randomize();
for(j=1;j<=J;j++)
for(i=1;i<=I;i++)
    v[j][i]=2.0*((float)rand()/RAND_MAX)-1.0;

/*Iteration Starts */

    q=0;

while(q<=qmax)
{
    e=0; q = q+1;
    printf(" \nIter no. = %d ",q);
    /* This portion randomises the order of Inputs */
    randomize();

    r1 = random(P);
    if(r1==0)
        p=1;
    else
        p=r1;

    ip=1;

    while (ip <=P)
    {
        for(i=1;i<=I;i++)
        {
            z1[i]=z[p][i];
        }

        for(k=1;k<=K;k++)
        {
            d1[k]=d[p][k];
        }

        /* compute net*/
        for(j=1;j<= J-1;j++)
        {
            s=0;
            for(i=1;i<= I;i++)
                s=s+v[j][i]*z1[i];
            m[j]=s;
        }
    }
}

```

```

/* compute f(net)*/
  for (j=1;j<=J-1;j++)
      y[j]= (2/(1.0+exp(-m[j]))) -1;
      y[J]=-1;

  for(k=1;k<=K;k++)
  {
      s=0;
      for( j=1;j<=J;j++)
          s=s+w[k][j]*y[j];
          n[k]=s;
      }
      for(k=1;k<=K;k++)
      {
          o[k]=(2/(1.0+exp(-n[k]))) -1;
      }
}

/* error computation*/
  for(k=1;k<=K;k++)
      e=e+(d1[k]-o[k])*(d1[k]-o[k])/2;

/* error correction */
  for(k=1;k<=K;k++)
      ed[k]= (d1[k]-o[k])*(1-o[k]*o[k])/2.0;

/* hidden layer error sig */
  for(j=1;j<=J;j++)
  {
      ds1=0;
      for(k=1;k<=K;k++)
          ds1= ds1 + ed[k]*w[k][j];
          ds[j]= ds1*(1-y[j]*y[j])/2.0;
      }

/* output layer wts*/
  for (k=1;k<=K;k++)
      for(j=1;j<=J;j++)
          w[k][j]=w[k][j]+ita*ed[k]*y[j];

/* hidden layer wts */
  for(j=1;j<=J;j++)
      for(i=1;i<=I;i++)
          v[j][i]=v[j][i]+ita*ds[j]*z1[i];

/* input next z */

  p =p+1;
  if(p > P)
      p= 1;
      ip=ip+1;
} /* end of for loop for inputting all z. */

```

```

        e=sqrt(e)/(P*K);
        gotoxy(5,60);
        printf("\t\t Error is e = %.5f \n",e);
if(( e<=emax) || ( q > qmax))
{
        printf("\n Process is terminated..\n\n");
        printf("\n Error is = %.5f\n ",e);

        /* Print the Final wts */
printf("\n\t Final Hidden to Output layer wts are :\n\n");
        for(k=1;k<=K;k++)
        for(j=1;j<=J;j++)
        printf("\t w[%d][%d]=%.5f  ",k,j,w[k][j]);
        printf("\n");
        printf("\n\t Final Input to Hidden layer wts are :\n");
        for(j=1;j<=J;j++)
        for(i=1;i<=I;i++)
        printf("\t v[%d][%d]=%.5f \n ",j,i,v[j][i]);

        break;

} /* End of for loop */

} /* end of while loop(q<qmax) */

        printf("\n To try one more J, Press any key; ");
        printf("otherwise to stop,type 'Y' or 'y' \n");
        c = getche();
        if(c == 'Y' || c== 'y')
        break;

} while((c != 'Y')); /*end of outer while loop */

/* printf(" \n Enter value of t:");
scanf("%d",&t);
if(t==0)
        exit(0);
else
{
for (p=1;p<=t;p++)
{
*/
for(k=1;k<=K;k++)
o[k]=0;
        clrscr();

```



```

printf(" \n Reading the test data ..");

for(i=1;i<=I-1;i++)
    fscanf(fp3,"%f",&z1[i]);
z1[I]= -1;
for(i=1;i<=I;i++)
    printf("z=%f",z1[i]);

/* printf("Enter # of sets of test data...\n");
scanf("%d", &t);
printf("Enter the test data...");
for(k=1;k<=t;k++)
    for(i=1;i<=I-1;i++)
        scanf("%f",&z[k][i]);
for(r=1;r<=t;r++)
{
    for(i=1;i<I;i++)
        z1[i]=z[r][i];
z1[I]=-1;    */

for(j=1;j<=J-1;j++)
{
    s=0;
    for(i=1;i<=I;i++)
        s=s+v[j][i]*z1[i];
    m[j]=s;
}

for(j=1;j<=J-1;j++)
y[j]= (2/(1.0+exp(-m[j]))) -1;
y[J]= -1;

for(k=1;k<=K;k++)
{
    s=0;
    for(j=1;j<=J;j++)
        s=s+w[k][j]*y[j];
    n[k]=s;
}

for(k=1;k<=K;k++)
{
o[k]=(2/(1.0+exp(-n[k]))) -1;
printf("\n O[%d]= %.3f ",k,o[k]);

fprintf(fp5,"\n the value of o[%d]= %f ", k,o[k]);
}

fclose(fp5);
printf("\n program end");
}

```