

# CHAPTER - 4

## CHAPTER - 4

Hardware description in chapter-3 will now become meaningful to the reader to develop an insight of the proposed design. It was rather difficult for us to discuss the integrated view of the VCRQ system designed. But we shall discuss the software in such a manner that an integrated perspective of the system becomes transparent.

The chapter is subdivided into five sections starting from the description of keyboard interface to the details of each measurement module.

### 4.1 : THE KEYBOARD INTERFACE

Before we discuss details of the interface software let us summarise the overall activity of the keyboard.

The keyboard has seventeen different specific function keys. Table(4.1) provides keys and corresponding codes for these. The keys R,V,C are meant to initiate a mode of measurement. The measurement actually begins after the required parameters are correctly entered. After each parameter entry the ENTER key works as a carriage return. Nevertheless, a few parameters could be selected as default parameters also. Upon system enters into a measurement, it would continue in the same mode till a RESET key is pressed.

As far as parameter entry is concerned the parameters are entered in the encoded form, using the numeric & symbol key closures. Each mode of measurement uses a very simple encoding scheme, as far as user is concerned.

CONTROL PORT ADDRESS TABLE : 4.2

Sr.No.	CONTROL PORT	ADDRESS
1]	Measurement-selection port (CTRLPRT1)	04H
2]	HELP Port (CTRLPRT2)	08H
3]	ERROR Port (CTRLPRT3)	0CH
4]	Indicator Port (CTRLPRT4)	10H
5]	TC select Port (CTRLPRT5)	14H
6]	DAC Port (CTRLPRT6)	18H
7]	R-latch Port (CTRLPRT7)	1CH
8]	V-latch Port (CTRLPRTV)	20H
9]	C-latch Port (CTRLPRTC)	24H
10]	8279 command port (CTRLPRT8)	01H
11]	8279 Data Port (CTRLPRT9)	00H
12]	High-byte port (CTRLPRTA)	28H
13]	Low-byte port (CTRLPRTB)	2CH

ERROR-MENU TABLE : 4.3a

Sr.No.	Type of Error	Code
1]	Enter Error	02H
2]	OVERRANGE	01H
3]	Parameter	04H
4]	ERROR clear	00H

INDICATOR-MENU TABLE : 4.3b

Sr.No.	Type of Error	Code
1]	R-measurement	01H
2]	V-measurement	02H
3]	C-measurement	04H
4]	Tanδ-measurement	08H
5]	Freq.-measurement	10H

HELP-MENU TABLE : 4.3c

SR.NO.	TYPE OF HELP	EQUIVALENT CODE
1]	ENTER-Help	01H
2]	Parameter-Help	02H
3]	Fmax-Help	04H
4]	Fmin-Help	08H
5]	Width-Help	10H
6]	DASH-Help	20H
7]	Enter-Parameter Help	03H
8]	Help-clear	00H

We wish to emphasise the software description of the keyboard/Display controller 8279 & the associated components. The device can be invoked either in command mode or data mode. Command mode avails the a set of commands, as per his requirements. Various ways of keyboard entry & display formats are possible. But one thing is important to note here that before sending the data for the required action, the required command word should precede the data.

In our system we initialise the 8279 with the prescalar adjusted to 31, two key lockout mode for keyboard & 8-character right entry mode for display & OOH as the blanking code for the display during blanking period. The prescalar has been adjusted to 31 because the clock frequency of the microcomputer system is nearly 3.1 MHz & the prescalar divides this frequency by 31 so that the scanning rate is 100kHz. The two key lock-out mode has been selected mainly because the keycodes are the single key code entries at a time. The hardware description of the circuit is already discussed in section 3.6.

The command & data is transferred to the controller chip by setting its correct address (sec 3.6). Another important point to be noted is a set of eight LED's, which indicate the error. These LED's are also useful for the user to takeup next step of action. Table 4.3a, gives types of errors indicated by these LED's.

KEY CODES : 4.1

Sr.No.	Key Type	Code
1]	0-Key (-Key-0)	00H
2]	1-Key (-key-1)	01H
3]	2-key (-key-2)	02H
4]	3-key (-key-3)	03H
5]	4-key (-key-4)	04H
6]	Reset (-key-5)	05H
7]	V-measure (-key-6)	06H
8]	R-measure (-key-7)	07H
9]	C-measure (-key-8)	08H
10]	ENTER (-key-9)	09H
11]	'—' (-key-10)	0AH
12]	1kHz (-key-11)	0BH
13]	10kHz (-key-12)	0CH
14]	100kHz (-key-13)	0DH
15]	1mHz (-key-14)	0EH
16]	10mHz (-key-15)	0FH
17]	Width-8 steps (-key-16)	10H
18]	17steps (-key-17)	11H
19]	35 steps (-key-18)	12H

#### 4.2 : KEY ENTRY FLOWCHART

The keys and their codes are given in table 4.1.

The first step is to initialize the chip 8279. The command word OOH selects the device 8279 in the keyboard/display format as per the requirements, discussed earlier. The command word 3FH adjusts the prescalar to the base value 31, while the command word COH selects the blanking format for blanking of the display. In our system, an output active low turns off the segment. So OOH is the blanking format used.

Before going to the measurement procedure user has to select the mode of measurement. The measurement mode is selected by using the symbol keys. But unless & until the carriage return (using ENTER key) is pressed the system is not invoked in actual measurement procedure. If the keys other than the carriage return are pressed, the system displays the type of error & also initializes the help to the user for correct action. Also if the key other than function-select key is pressed it indicates the "parameter error" & initiates the help to the user for the correct entry. The selection of type of measurement is carried out by comparing the key pressed with the keycodes of the function keys.

#### 4.3 : V-MEASUREMENT SOFTWARE

As the V-measurement set up is designed around multichannel thermocouple input system, the mode selection of the thermocouple (ref.table 3.4) by the user, is the first part in measurement process. Only numeric key entries

are allowed for thermocouple selection. No default TC mode selection is allowed in this case. If the user attempts to make wrong entry, error routine is initialized to glow the correct error on the LED's.

Upon correct TC selection, the system is invoked for actual measurement procedure. The control words for TC selection are in an array from the base address BADDRTC. From encoded keycodes the correct number of TC mode is determined & is latched in the control port-5 (CTRLPRT5).

We shall discuss the software aspects of autoranging (Hardware aspects are already discussed in chapter-3). Autoranging means, to adjust the measurement system in the correct range of the measurand. This is achieved as follows.

We know that the maximum input voltage accepted by the system is 4.096V (for ADC ref.of 2V). So the range corresponding to this particular voltage should be selected first. In otherwords we start with the highest range & step down the ranges until overflow occurs. The overflow is the indication to the autoranger that the input measurand is in the range just above the present range & hence the system steps upward for the in-range. The procedure is so designed that the ADC is always protected from the permanent damage.

As shown in the flowchart, after selecting the highest range if the input value is  $4.096 < V_{in} < 5V$ , overrange occurs. Overrange is confirmed by detecting the overflow flag. The system has an access to the overflow flag through the output from the ADC. Overflow flag is read along with

the four MSB's of the ADC, denoted as Hbyte.. & then comparing it with the overflow bit. So if overflow occurs in the highest range itself, it is called "OVERRANGE". The system indicates the overrange by glowing the overrange LED. If the overrange occurs in a range, which is not highest range, the range is stepped towards the higher range. If the overflow flag is not set then it will compare the ADC output with the binary value 0190H. If the ADC output is greater than 400 (190H) then it will find itself in-range & call the display routine. On the otherhand if the ADC output is less than 400, then the system will step to the lower range. The control words of range switching are accessed from an array at BADDRV knowing the range numbers. Range numbers are indicated in table 3.3.

One important thing to be noted here is, while stepping down the ranges, the system first checks itself, for the lowest range & if it is in the lowest range it will display the answer in the lowest range, as it is. We are going to devote one complete section for the display & binary to BCD conversion. So in the present discussion it is assumed that the answer is displayed in its correct form.

After displaying the answer, the measurement system resumes in the same range & repeats the sequence.

#### 4.4 : R-MEASUREMENT SOFTWARE

On the parallel lines we can discuss the R-measurement software. The "parameter selection" software, as for V-measurement, is not required for R-measurement. The table

3.2b shows the control-word format of R-measurement, for various ranges. The total number of ranges allowed in this measurement is seven with the lowest range, at 40 ohms & the highest at 4-meg ohm,in decades. The ranges vary in decades.

As usual, the highest range of  $4\text{m}\Omega$  is set initially. The value 4 is of particularly selected because for the range 4 meg ohms, the current source sources 1 microampere current through 4 megohm resistor so as to develop the maximum voltage drop of 4.0 volts across the unknown resistor (in this case 4 megohm).

When the range switches from 4 megohm to 400 kilo ohms, the sourcing current requirement increase by a factor of ten. i.e. 10 micro ampere. For the last range of 40ohms, it may appear that, the current generator will have to source the current of value one ampere. Although, logically it is true but in this case, we switch the measurement range of the ADC from  $0 - \pm 4\text{V}$  to  $0 - \pm 400\text{ mV}$ . In this ADC range, the maximum input voltage of 400 mV will produce the full-scale output. Thus for the lowest range of 4 ohms the sourcing current requirements become 100 mA to produce the full-scale output of 400 mV. That is why we select the last three-ranges of  $400\Omega$ ,  $40\Omega$  &  $4\Omega$ , in the ADC range of 0 to  $\pm 400\text{ mV}$ , while the first four ranges are select the ADC range of 0 to  $\pm 4.0$  volts (table 3.2b).

The autoranging scheme for R-measurement is similar to that for V-measurement. We a firm that in V-measurement ADC output is checked for overflow flag to switch to the higher

range or the comparision with 400 (0190H) selects the lower range. In R-measurement the same strategy is used, as we are to represent the resistance in terms of the corresponding voltage itself. The only difference in the autoranging scheme for R-measurement from that of V-measurement scheme is the total number of ranges. In V-measurement we have four ranges, while in R-measurement we have seven ranges. So the base-address for R-measurement BADDRR, has to increment seven times, at the most, to approach the lowest range. The control word format for the R-measurement is shown in table 3.2b. The lower range is stepped by incrementing the bare-address BADDRR, by one. But before stepping down from any range the system always checks that it is not in the last. If it is range, the system displays the answer in the last range itself. While stepping up the system checks whether it is in the highest range or not. If it is in the highest range then the overrange of the reading is indicated. The system displays answer only when it is in range. After displaying the answer, the system goes back for reading the ADC & displays the in range output.

#### 4.5 : C-MEASUREMENT SOFTWARE

The C-measurement software is subdivided into two groups 1] Parameter Entry Software 2] The measurement software.

**1] PARAMETER ENTRY SOFTWARE :**

Refer to the flow chart no.4. The required parameters for C-measurement are 1] Selection of the frequency range i.e. minimum frequency range Fmin & maximum frequency range Fmax, of interest 2] Width count, to specify the number of steps, the system should take while sweeping through the frequency range. Both these parameters are either user-selected or these are treated as default parameters by the system. Even the facility is provided to select one parameter as default, while the other parameter as user specified. Every parameter entry is accepted only if there is a carriage return (ENTER key). As shown in the flowchart no.4, initially the system asks for Fmin using the encoded numeric keys or instruct the system to consider it as the default parameter, by pressing the carriage return. Then the system asks for the 2nd & the 3rd parameter Fmax & width count. The entry mode is same as that for Fmin. Upon selecting the width parameter, the system loads the width-decrement count specific to the width count (table 4.4). Upon carriage return the system proceeds for the measurement.

**2] MEASUREMENT SOFTWARE :**

The parameter values are stored in the memory area allotted for it. The C-measurement is selected by sending a control word (C-select) to the function selector latch. As shown in the flowchart no.5, the measurement starts from the Fmin selected. From table 3.6e, it is apparent that for

each frequency decade the allowed values of capacitance ranges are different. So also the control words for the same capacitance range is different for each frequency decade. Initially the Fcount is selected to decimal 180. FCount at 180 will select the minimum frequency in that decade e.g. 100 Hz, for the frequency range selection of 1kHz (table 4.4). The width count & width decrement count is also appropriately set to sweep the frequency in the frequency range selected. The Fcount value is sent as a word to the D/A converter via latch LS373 (IC21), which in turn provides the sweep voltage to the VCO (XR-205) as already discussed in section 3.7 & 3.7.1. The Crange value (initially Cmax) is passed as a control word to the C-latch IC22. Referring to table.. we find that C-range control word performs two actions. One, selection of the capacitor for setting the free-running frequency of the VCO & second is, the selection of current limit resistance R, for the desired range of frequency & capacitance.

Now the ADC is read by the microcomputer system through the control ports A & B. Control port A (CTRLPRTA) is used to read Highbyte, while CTRLPRTB is used to read the Lowbyte. The Highbyte includes the state of polarity & overflow flag. If overflow is detected, the software checks whether it is highest C-range for the frequency range. If it is the highest Crange, then the system exits out of the C-measurement procedure otherwise the software follows autoranging scheme. If there is no overflow, the system checks whether the underrange conditions. If there exists

possible lower range, it jumps to the lower range. The possibility is checked by comparing the ADC output with the decimal value of 400. If ADC output is greater than the base value it means the system is in range. Before selecting the lower range the system checks itself for the lowest range. If it is the lowest range, the system displays the reading as it is encountered.

If the ADC value is in range the display routine for 'C' is initiated. It displays the value of 'C' along with its unit. Upon carriage-return the system displays the value of frequency & upon accepting next carriage-return the system displays  $\tan\delta$  value.

During  $\tan\delta$  measurement, the analog multiplexing switch, IC49 connects the  $\tan\delta$  measurement output to the ADC input. As we known in  $\tan\delta$  measurement we measure the inphase component of the complex impedance. After displaying the  $\tan\delta$  value the system waits for the carriage return from the user to resume the measurement procedure. The system first checks the widthcount value (i.e. number of frequency steps in a frequency decade). If the widthcount value has not decremented to zero then next frequency value Fcount is set & the procedure is repeated. If the width count has decremented to zero then the system sets the next frequency range & checks whether it has exceeded the value Fmax specified by the user. If it has exceeded Fmax, it will come out of the measurement procedure otherwise it will set the next frequency range. It determines the appropriate Cmin & Cmax ranges for the next frequency decade & enters

into the measurement procedure again.

#### 4.6 : DISPLAY SOFTWARE

The display software for each of the measurements is discussed separately in this section. The overall structure of the display software includes (1) Binary to BCD conversion (2) BCD to seven segment code conversion (3) Display of the units (4) Display of the answer.

##### 4.6.1 : V & R MEASUREMENT DISPLAY SOFTWARE

The first step is to convert the binary answer from the ADC into an equivalent BCD form. This is achieved as follows. Firstly the binary value is checked for greater than 1000. If it is greater, it is divided by 1000 till it is less than 1000. During division a counter is set. The counter holds BCD3. When the binary value is a hundred's multiple it is divided by 100 till it is less than 100. Again a counter is set to hold BCDO. Then the remainder is divided by 10 using the similar steps & the counter holds the BCD1 while remainder is BCD. These BCD values are called unpacked BCDS. The BCD values are converted to equivalent segment codes & are stored in the memory area reserved for display information.[BUFFLOC]

Depending upon the range, the unit & dot point logic is selected. For example in case of V-measurement if the range is 03H, then as shown in table 3.3 it corresponds to 40mV's range (39.99mV). So the dot appear on the right side of the 2nd digit, while the unit "mV" will appear on the

alphanumeric displays. The dot logic & unit for each range is fixed. So the microcomputer's job is to check the range of the answer of measurement & load the dot logic & unit in the memory area reserved for display information. [BUFFLOC]

The display information is transferred to the display controller using the software routine BUFFOUT which initializes the 8279 in load Display-RAM mode & transfers the display information.

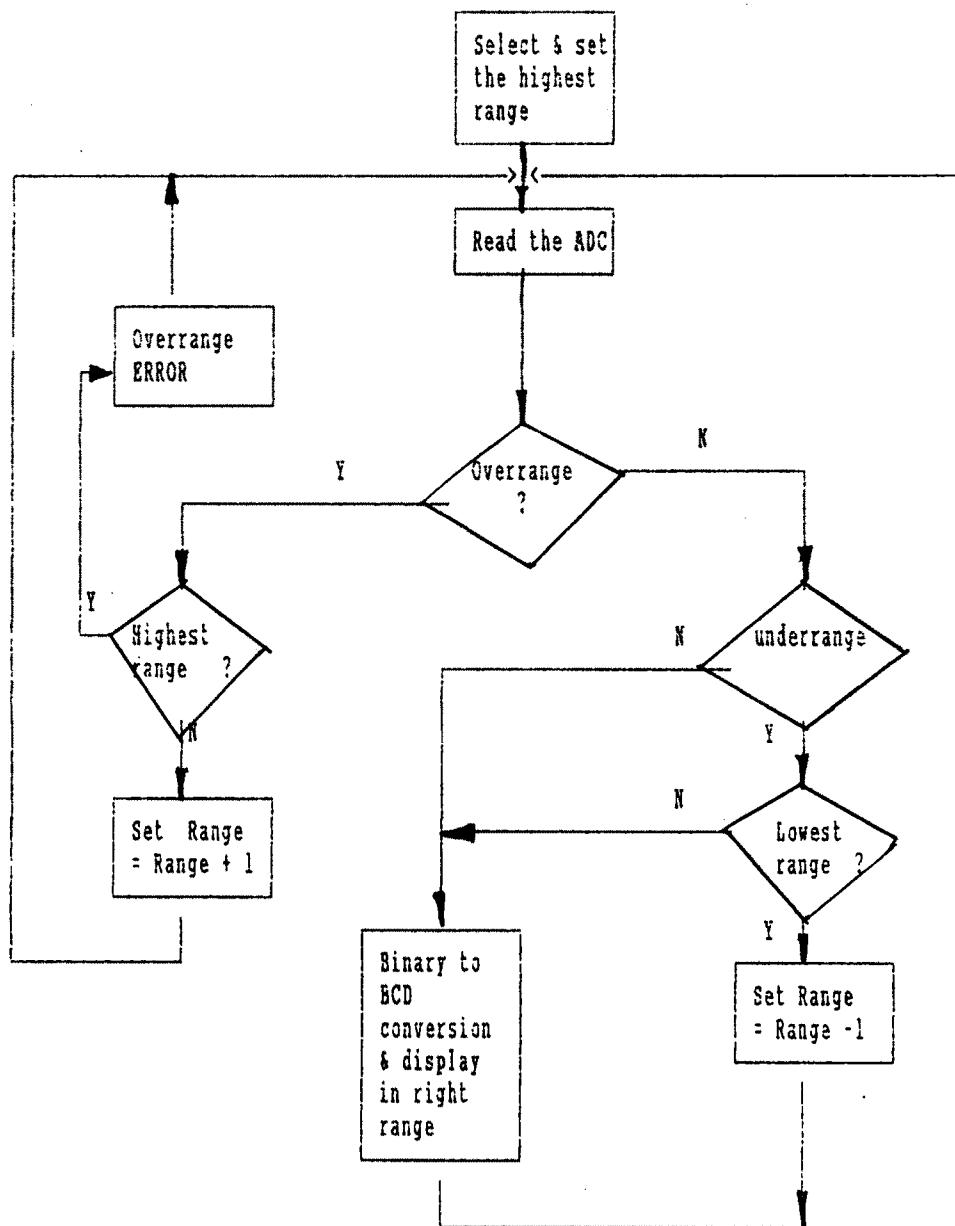
#### C-MEASUREMENT DISPLAY SOFTWARE

It includes the display softwares for frequency display, capacitance display & tan $\delta$  display.

The capacitance display format is similar to that of the V & R measurement display format. For the frequency display, instead of directly displaying the frequency value, the system displays the values of the Frange, the Fcount & the width count. From the display, user can look for the correct value of frequency in the look-up table.... A point to be noted here is that the value of ADC in case of capacitance measurement is corrected to its right BCD form using a lookup table in memory. Instead of calculating the value of capacitor from the ADC value, we have preferred this choice. This would lead to faster capacitance measurement, or infact any other <sup>of</sup> form of reactance value. This point is further discussed in conclusion-section.

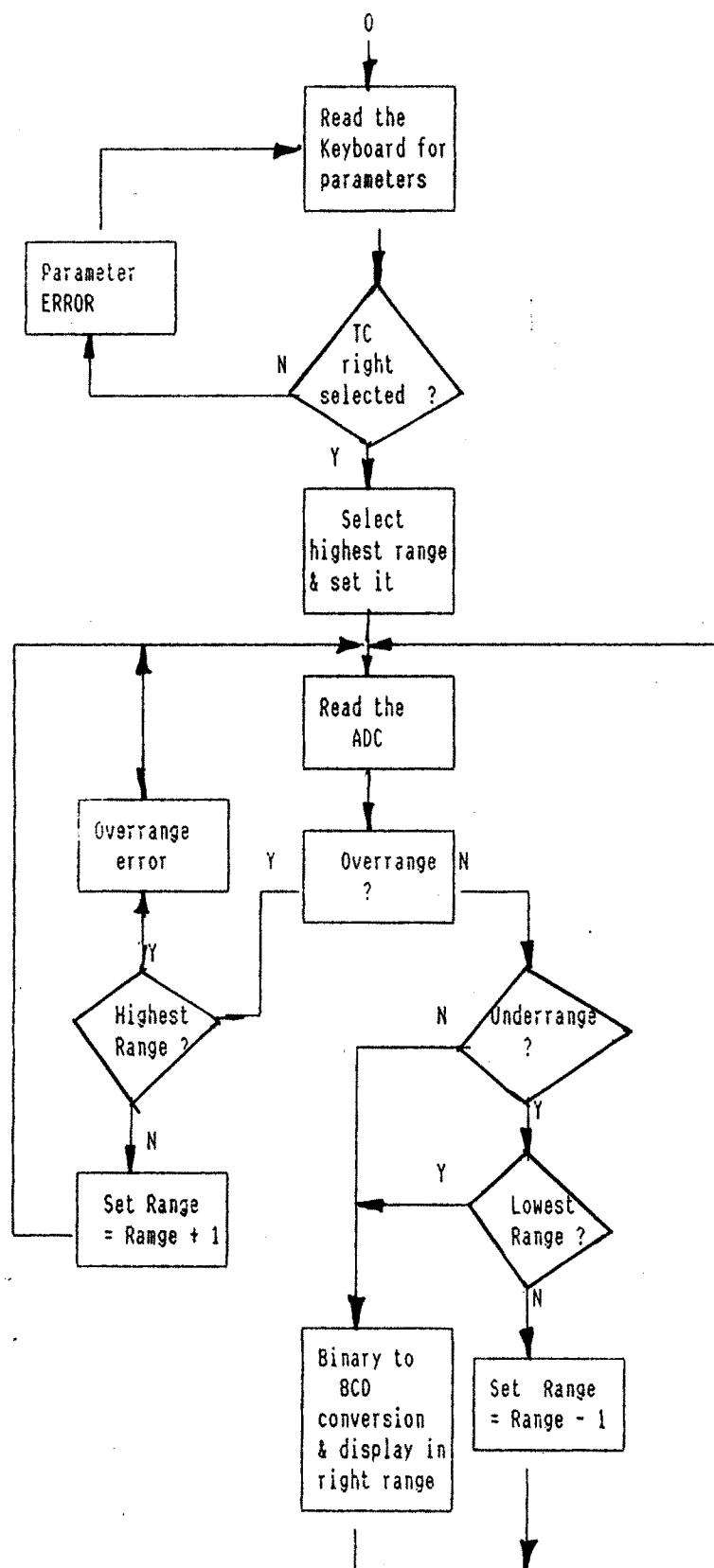
R-measurement Starts

Flow Chart No.2



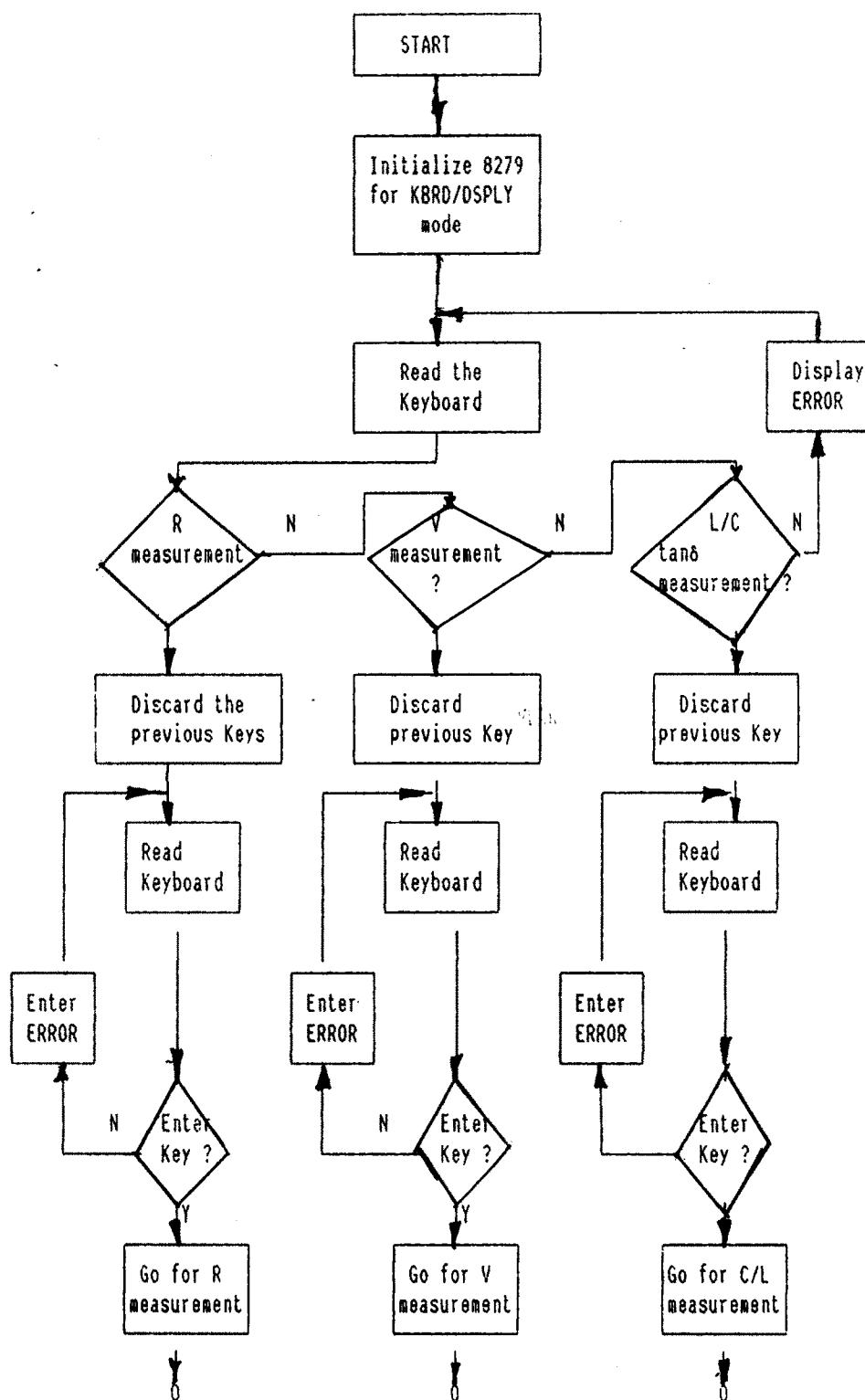
V-measurement Starts

Flow Chart No.3

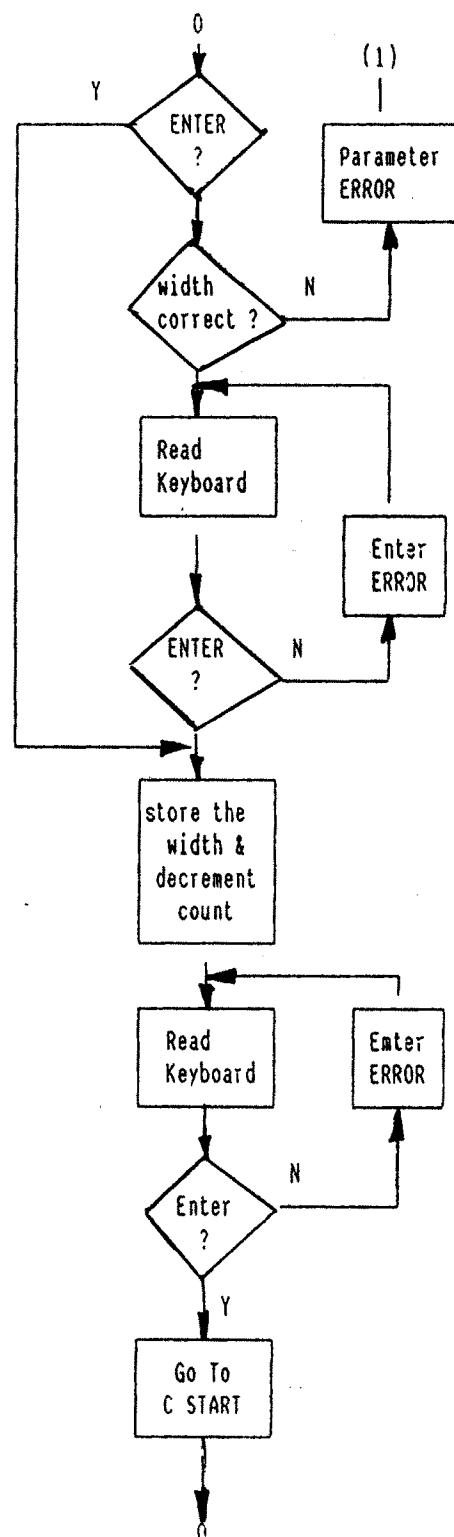


Flow Chart No.1

## KEY ENTRY FLOW CHART FOR VLCRQ METER

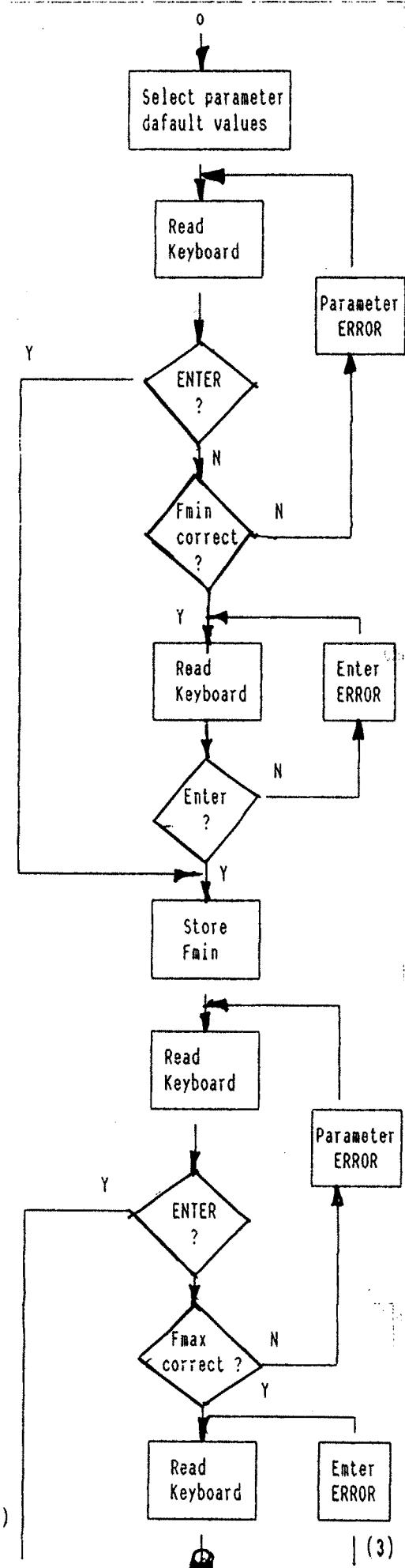


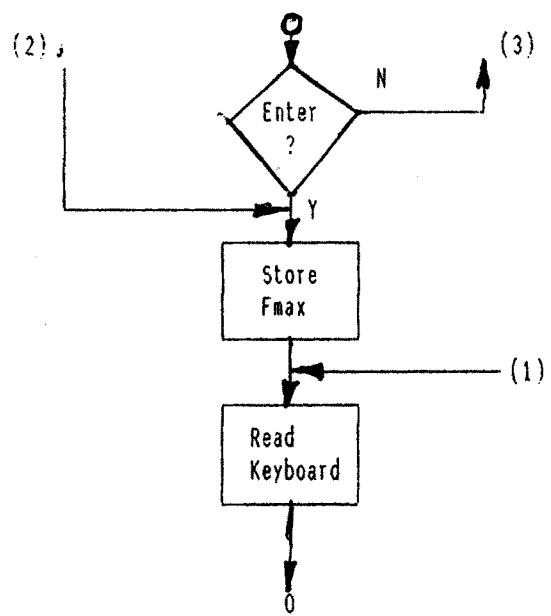
Flow Chart No.4

C-measurement

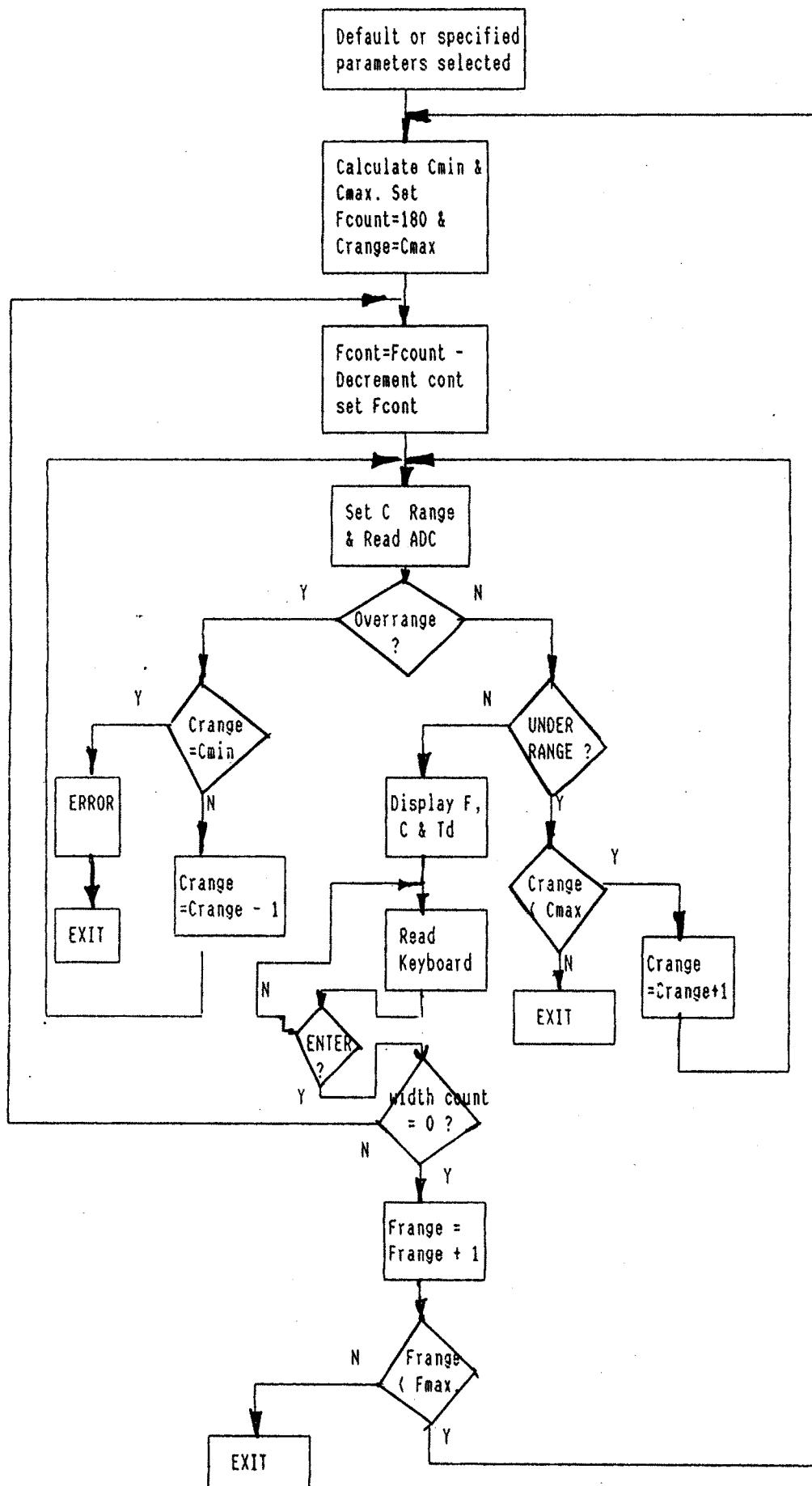
Flow Chart No.4

## L/C-MEASUREMENT PARAMETERS SELECTION FLOW CHART





Flow Chart No.5

C measurement Starts

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364  
 SOURCE FILE NAME: VLCRQI.ASM

```

;MEASUREMENT SYSTEM TO MEASURE THE PARAMETERS
;V, R, C & Td.
;
0001 ENT_HLP: EQU 01H ; help menu
0002 PARA_HLP: EQU 02H
0004 FMAX_HLP: EQU 04H
0008 FMIN_HLP: EQU 08H
0010 WID_HLP: EQU 10H
0020 DASH_HLP: EQU 20H
0003 ENPA_HLP: EQU 03H
0000 HLP_CLR: EQU 00H
;
; error menu
0002 ENTERR__: EQU 02H
0001 OVRERR__: EQU 01H
0004 PARAERR__: EQU 04H
0000 ERRCLR__: EQU 00H ; measurement ind
;
0001 RMEASLED: EQU 01H
0002 VMEASLED: EQU 02H
0004 CMEASLED: EQU 04H
0008 TDMESLED: EQU 08H
0010 FMEASLED: EQU 10H
;
; control ports
0026 CTRLPRT1: EQU 26H ; selection port
0021 CTRLPRT2: EQU 21H ; help port
;
CTRLPRT3: EQU 20H ; error port
;
CTRLPRT4: EQU 22H ; indicator port

```

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364

SOURCE FILE NAME: VLCROI.ASM

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364

SOURCE FILE NAME: VLCRQI.ASM

```

000F      ;  

          __KEY_15:    EQU    0FH ; 10 MHz parameter  

0010      ;  

          __KEY_16:    EQU    10H ; width-8 step  

0011      ;  

          __KEY_17:    EQU    11H ; width-17 step  

;  

;  

;               ; measurement selection  

;  

0001      R_SELECT:   EQU    01H ; control words  

0002      V_SELECT:   EQU    02H  

0003      C_SELECT:   EQU    03H  

0004      TDSELECT:   EQU    04H  

;  

FFF8      CMPLMNT1:   EQU    0FFF8H ; 2's complement of 100  

;  

009C      CMPLMNT2:   EQU    009CH ; 2's complement of 100  

;  

0000      SEGCODV1:   EQU    00H ; 7-segment codes to dis  

0000      SEGCODV2:   EQU    00H  

;  

0000      SEGCODR1:   EQU    00H ; codes to display Ohm.  

0000      SEGCODR2:   EQU    00H  

;  

0000      SEGCODF1:   EQU    00H ; codes to display freq.  

0000      SEGCODE2:   EQU    00H  

;  

0000      SEGCOD00:   EQU    00H ; codes to display " 0 "  

0000      SEGCOD01:   EQU    00H  

;  

0000      SEGCOD10:   EQU    00H ; codes to display " 1 "  

0000      SEGCOD11:   EQU    00H  

;  

0000      SEGCOD20:   EQU    00H ; codes to isplay "2"  

0000      SEGCOD21:   EQU    00H  

;  

0008      WIDTH_1:    EQU    08H ; width count  

;  

WIDTH_2:    EQU    11H  

WIDTH_3:    EQU    23H

```

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364

SOURCE FILE NAME: VLCRQI.ASM

```

0014      ; DCRCNT_1:      EQU    14H ; decrement count
000A      ; DCRCNT_2:      EQU    0AH
0005      ; DCRCNT_3:      EQU    05H
2000      RESETLOC:      EQU    2000H ; on reset jump to
;                                ; start of the program
;
0000 00000000 BADDR_TC:      DB     00, 00, 00, 00, 00, 00, 00,
000B 00000000 ;                                DB     00, 00, 00, 00, 00, 00, 00, 00
0014 00000000 BADDR_V:      DB     00, 00, 00, 00
0018 00000000 BADDR_R:      DB     00, 00, 00, 00, 00, 00
001E 00000000 BADDR_C:      DB     00, 00, 00, 00, 00, 00, 00, 00
002A 00000000 CRNGCWRD:    DB     00, 00, 00, 00, 00, 00, 00, 00
0034 00000000 ;                                DB     00, 00, 00, 00, 00, 00, 00, 00,
003E 00000000 ;                                DB     00, 00, 00, 00, 00, 00, 00, 00,
0048 0000 ;                                DB     00, 00
004A 00000000 LOOK_TAB:    DB     00, 00, 00, 00, 00, 00, 00, 00,
0054      ; BADDRROM:      DS     4096H
0054      ; BUFFLOC:       DS     08H
0054      ; TEMPLOC:       DS     07H
005B      ; DFALTLOC:     DS     04H
005F 0000 UNIT1:          DB     00,00 ; Blank Codes
0061 0000 UNIT2:          DB     00,00
0063 0000 UNIT3:          DB     00,00
0065 0000 UNIT4:          DB     00,00
0067 0000 UNIT5:          DB     00,00
;
CRNG1 :           DB     00,00,00,00
CRNG2 :           DB     00,00,00,00

```

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364

SOURCE FILE NAME: VLCROI.ASM

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364

SOURCE FILE NAME: VLCRQI.ASM

```

0101 FE06      ;          CPI      KEY_6
0103 CA1701    ;          JZ       VMEASURE
0106 FE07      ;          CPI      KEY_7
0108 CA5D02    ;          JZ       RMEASURE
010B FE08      ;          CPI      KEY_8
010D CAC803    ;          JZ       CMEASURE
0110 3E04      ;          MVI     A, PARAERR_
0112 D320      ;          OUT     CTRLPRT3
0114 C3F200    ;          JMP     KYCHK
;
;
;-----VMEASUREMENT STARTS-----
;
0117 3E01      VMEASURE:      MVI     A, ENT_HLP
0119 D321      ;          OUT     CTRLPRT2
011B DB19      KYCHK0:       IN      CTRLPRT8
011D E601      ;          ANI     01H
011F CA1B01    ;          JZ      KYCHK0
0122 3E40      ;          MVI     A, 40H
0124 D319      ;          OUT     CTRLPRT8
0126 DB18      ;          IN      CTRLPRT9
0128 E63F      ;          ANI     3FH
012A FE09      ;          CPI      KEY_9
012C CA3601    ;          JZ      KYCHK1
012F 3E02      ;          MVI     A, ENTERR_
0131 D320      ;          OUT     CTRLPRT3
;
;-----KYCHK1-----
;          JMP     KYCHK0
;          MVF     A, ERRCLR_

```

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364

SOURCE FILE NAME: VLCRQI.ASM

0138 D320	;	OUT	CTRLPRT3
013A 3E02	;	MVI	A, PARA_HLP
013C D321	;	OUT	CTRLPRT2
013E 3E02	;	MVI	A, VMEASLED
0140 D322	;	OUT	CTRLPRT4
0142 DB19	KYCHK2:	IN	CTRLPRT8
0144 E601	;	ANI	01H
0146 CA4201	;	JZ	KYCHK2
0149 3E40	;	MVI	A, 40H
014B DB18	;	IN	CTRLPRT9
014D E63F	;	ANI	3FH
014F FE01	;	CPI	01H
0151 F25B01	;	JP	KYCHK3
0154 3E04	ERROR1:	MVI	A, PARAERR_
0156 D320	;	OUT	CTRLPRT3
0158 C34201	;	JMP	KYCHK2
015B FE05	KYCHK3:	CPI	05H
015D FA6301	;	JM	KYCHK4
0160 C35401	;	JMP	ERROR1
0163 87	KYCHK4:	ADD	A
0164 87	;	ADD	A
0165 47	;	MOV	B,A
0166 3E00	;	MVI	A, ERRCLR_
		OUT	CTRLPRT3
		MVI	A, DASH_HLP

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364

SOURCE FILE NAME: VLCRQI.ASM

016C D321	;	OUT	CTRLPRT2
016E DB19	KYCHK5:	IN	CTRLPRT8
0170 E601	;	ANI	01H
0172 CA6E01	;	JZ	KYCHK5
0175 3E40	;	MVI	A, 40H
0177 D319	;	OUT	CTRLPRT8
0179 DB18	;	IN	CTRLPRT9
017B E63F	;	ANI	3FH
017D FE0A	;	CPI	<u>KEY_10</u>
017F CA8901	;	JZ	KYCHK6
0182 3E04	;	MVI	A, PARAERR_
0184 D320	;	OUT	CTRLPRT3
0186 C36E01	;	JMP	KYCHK5
0189 3E00	KYCHK6:	MVI	A, ERRCLR_
018B D320	;	OUT	CTRLPRT3
018D 3E02	;	MVI	A, PARA_HLP
018F D321	;	OUT	CTRLPRT2
0191 DB19	CHECK6:	IN	CTRLPRT8
0193 E601	;	ANI	01H
0195 CA9101	;	JZ	CHECK6
0198 3E40	;	MVI	A, 40H
019A D319	;	OUT	CTRLPRT8
019C DB18	;	IN	CTRLPRT9
019E E63F	;	ANI	3FH
		CPI	01H
		JP	KYCHK7



AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364

SOURCE FILE NAME: VLCRQI.ASM

```

        ;          ERROR2:      MVI    A,PARAERR_
01A5 3E04      ;          OUT    CTRLPRT3
01A7 D320      ;          JMP    CHECK6
01A9 C39101    ;          KYCHK7:    CPI    05H
01AC FE05      ;          JM     AHEAD
01AE FAB401    ;          JMP    ERROR2
01B1 C3A501    ;          AHEAD:    ADD    B
01B4 80        ;          LXI    H,BADDR_TC
01B5 210000    ;          ADD    L
01B8 85        ;          MOV    L,A
01B9 6F        ;          MOV    A,M
01BA 7E        ;          OUT    CTRLPRT5
01BB D323      ;          ;
01BD D326      ;          OUT    CTRLPRT1
01BF 3E00      ;          MVI    A,ERRCLR_
01C1 D320      ;          OUT    CTRLPRT3
01C3 211400    ;          LXI    H,BADDR_V
01C6 7E        ;          NXTRNG:   MOV    A,M
01C7 D325      ;          OUT    CTRLPRTV
01C9 DB28      ;          ADCIN:    IN     CTRLPRTB
01CB 4F        ;          MOV    C,A
01CC DB27      ;          IN     CTRLPRTA
01CE 47        ;          MOV    B,A
01CF E610      ;          ANI    10H
                                JR     CHKUMDR
                                MOV    A,L

```

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364  
 SOURCE FILE NAME: VLCRQI.ASM

```

01D5 FE00      ;          CPI    00H
01D7 C2DF01      ;          JNZ    CHNGRNG
01DA 3E01      ;          MVI    A,OVRERR_
01DC C3C901      ;          JMP    ADCIN
01DF 2D      CHNGRNG:      DCR    L
01E0 C3C601      ;          JMP    NXTRNG
01E3 79      CHKUNDR:      MOV    A,C
01E4 FEE8      ;          CPI    0E8H
01E6 F2F401      ;          JP     CHKMSB1
01E9 78      ;          MOV    A,B
01EA E60F      ;          ANI    OFH
01EC FE04      ;          CPI    04H
01EE F20602      ;          JP     INRNG
01F1 C3FC01      ;          JMP    LWRRNG
01F4 78      CHKMSB1:      MOV    A,B
01F5 E60F      ;          ANI    OFH
01F7 FE03      ;          CPI    03H
01F9 F20602      ;          JP     INRNG
01FC 7D      LWRRNG:      MOV    A,L
01FD FE03      ;          CPI    03H
01FF CA0602      ;          JZ     INRNG
0202 2C      ;          INR    L
0203 C3C601      ;          JMP    NXTRNG
0206 78      INRNG:      MOV    A,B
;          ANI    OFH
;          STA    TEMPLOC+6

```

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364

SOURCE FILE NAME: VLCRQI.ASM

020C 79	;	MOV	A,C
020D 325900	;	STA	TEMPLOC+5
0210 CD1602	;	CALL	VDISPLAY
0213 C3C901	;	JMP	ADCIN
0216 E5	VDISPLAY:	PUSH	H
0217 CD5203	;	CALL	BCDCNVRT
021A 215B00	;	LXI	H,BUFFLOC+7
021D 3E00	;	MVI	A,SEGCODV1
021F 77	;	MOV	M,A
0220 23	;	INX	H
0221 3E00	;	MVI	A,SEGCODV2
0223 77	;	MOV	M,A
0224 E1	;	POP	H
0225 E5	;	PUSH	H
0226 7D	;	MOV	A,L
0227 CA3C02	;	JZ	LDRNG1
022A FE01	;	CPI	01H
022C CA4502	;	JZ	LDRNG2
022F FE02	;	CPI	02H
0231 CA4E02	;	JZ	LDRNG3
0234 FE03	;	CPI	03H
0236 CA5702	;	JZ	LDRNG4
0239 C3C601	;	JMP	NXTRNG
	LDNRG1:	LXI	D,UNIT1
		LXI	H,BUFFLOC

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364

SOURCE FILE NAME: VLCRQI.ASM

		JMP	ACTION
0242 C34603	;		
0245 116100	LDRNG2:	LXI	D,UNIT2
0248 215600	;	LXI	H,BUFFLOC+2
024B C34603	;	JMP	ACTION
024E 116100	LDRNG3:	LXI	D,UNIT2
0251 215500	;	LXI	H,BUFFLOC+1
0254 C34603	;	JMP	ACTION
0257 116100	LDRNG4:	LXI	D,UNIT2
025A 210000	;	LXI	H,BUFFLOC
025C C34603	;	JMP	ACTION
	;	;RMEASUREMENT STARTS HERE	
025D 3E01	RMEASURE:	MVI	A,ENT_HLP
025F D321	;	OUT	CTRLPRT2
0261 DB08	CHKKY1:	IN	CTRLPRT8
0262 E601	;	ANI	01H
0263 CA6102	;	JZ	CHKKY1
0266 3E40	;	MVI	A,40H
0268 D319	;	OUT	CTRLPRT8
026A DB18	;	IN	CTRLPRT9
026C E63F	;	ANI	3FH
026E FE09	;	CPI	KEY_9
0270 CA7A02	;	JZ	AHEAD1
0273 3E02	;	MVI	A,ENTERR_
0275 D320	;	OUT	CTRLPRT3
	;	JMP	CHKKY1
	AHEAD1:	MVI	A,RMEASLED

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364

SOURCE FILE NAME: VLCRQI.ASM

027C D304	;	OUT	CTRLPRT4
027D 3E01	;	MVI	A,R_SELECT
027E D326	;	OUT	CTRLPRT1
0280 3E00	;	MVI	A,HLP_CLR
0282 D321	;	OUT	CTRLPRT2
0284 3E00	;	MVI	A,ERRCLR_
0286 D320	;	OUT	CTRLPRT3
0288 211800	;	LXI	H,BADDR_R
028B 7E	NXTRNG1:	MOV	A,M
028C D300	;	OUT	CTRLPRTR
028E DB28	ADCIN1:	IN	CTRLPRTB
0290 4F	;	MOV	C,A
0291 DB27	;	IN	CTRLPRTA
0293 47	;	MOV	B,A
0294 E610	;	ANI	10H
0296 CAA702	;	JZ	CHKUNDRI
0299 7D	;	MOV	A,L
029A FE00	;	CPI	00H
029C 3E01	;	MVI	A,OVRERR_
029E D320	;	OUT	CTRLPRT3
02A0 C38E02	;	JMP	ADCIN1
02A3 2D	CHNGRNG1:	DCR	L
02A4 C38B02	;	JMP	NXTRNG1
	;	MOV	A,C
	CHKUNDRI:	CPT	0E8H

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364

SOURCE FILE NAME: VLCRQI.ASM

02A9 F2B702	;	JP	CHKMSB2
02AC 78	;	MOV	A,B
02AD E60F	;	ANI	0FH
02AF FE04	;	CPI	04H
02B1 F2C602	;	JP	INRNG1
02B4 C3BC02	;	JMP	LWRRNG1
02B7 78	CHKMSB2:	MOV	A,B
02B8 E60F	;	ANI	0FH
02BA FE03	;	CPI	03H
02BC CAC602	;	JP	INRNG1
02BC 7D	LWRRNG1:	MOV	A,L
02BD E606	;	ANI	06H
02BF CAC602	;	JZ	INRNG1
02C2 2C	;	INR	L
02C3 C38B02	;	JMP	NXTRNG1
02C6 78	INRNG1:	MOV	A,B
02C7 E60F	;	ANI	0FH
02C9 325A00	;	STA	TEMPLOC+6
02CC 79	;	MOV	A,C
02CD 325900	;	STA	TEMPLOC+5
02D0 CDD602	;	CALL	RDISPLAY
02D3 C38E02	;	JMP	ADCIN1
02D6 E5	RDISPLAY:	PUSH	H
02D7 CD5203	;	CALL	BCDCNVRT
		X1	4,0VFF40C+7

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364

SOURCE FILE NAME: VLCRQI.ASM

02DD 3E00	MVI	A, SEGCODR1
02DF 77	MOV	M,A
02E0 23	INX	H
02E1 3E00	MVI	A, SEGCODR2
02E3 77	MOV	M,A
02E4 E1	POP	H
02E5 E5	PUSH	H
02E6 7D	MOV	A,L
02E7 E60F	ANI	0FH
02E9 CA3D03	JZ	LDRNG11
02EC FE01	CPI	01H
02EE CA3403	JZ	LDRNG10
02F1 FE02	CPI	02H
02F3 CA2B03	JZ	LDRNG9
02F6 FE03	CPI	03H
02F8 CA2203	JZ	LDRNG8
02FB FE04	CPI	04H
02FD CA1903	JZ	LDRNG7
0300 FE05	CPI	05H
0302 CA1003	JZ	LDRNG6
0305 FE06	CPI	06H
0306 CA0000	JZ	LDRNG5
030A 215400	LXI	H,BUFFLOC
030D C34603	JMP	ACTION

LDRNG6 :

*MR. BALASUBRAMANIAN KHARUEKAR LIBRARY  
LXI 01 HADAR*

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364  
 SOURCE FILE NAME: VLCRQI:ASM

0313 215500	;	LXI	H,BUFFLOC+1
0316 C34603	;	JMP	ACTION
0319 116700	LDRNG7:	LXI	D,UNIT5
031C 215600	;	LXI	H,BUFFLOC+2
031F C34603	;	JMP	ACTION
0322 116500	LDRNG8:	LXI	D,UNIT4
0325 215400	;	LXI	H,BUFFLOC
0328 C34603	;	JMP	ACTION
032B 116500	LDRNG9:	LXI	D,UNIT4
032E 215500	;	LXI	H,BUFFLOC+1
0331 C34603	;	JMP	ACTION
0334 116500	LDRNG10:	LXI	D,UNIT4
0337 215600	;	LXI	H,BUFFLOC+2
033A C34603	;	JMP	ACTION
033D 116300	LDRNG11:	LXI	D,UNIT3
0340 215400	;	LXI	H,BUFFLOC
0343 C34603	;	JMP	ACTION
0346 3E01	ACTION:	MVI	A,01H
0348 B6	;	ORA	M
0349 77	;	MOV	M,A
034A CDA603	;	CALL	UNITDSP
034D CDB603	;	CALL	BUFFOUT
0350 E1	;	POP	H
0351 C9		RET	
0352 2A5900	BCDCNVRT:	LHLD	TEMPLOC+5
		LXI	D,(TEMPLOC)

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364  
 SOURCE FILE NAME: VLCRQI.ASM

0358 0E00		MVI	C,00H
035A 19	THOUSND:	DAD	D
035B D26203	;	JNC	ADJUST1
035E 0C	;	INR	C
035F C35A03	;	JMP	THOUSND
0362 11E803	ADJUST1:	LXI	D,03E8H
0365 19	;	DAD	D
0366 79	;	MOV	A,C
0367 325400	;	STA	BUFFLOC
036A 119C00	;	LXI	D,CMPLMNT2
036D 0E00	;	MVI	C,00H
036F 19	HUNDRED:	DAD	D
0370 D27703	;	JNC	ADJUST2
0373 0C	;	INR	C
0374 C36F03	;	JMP	HUNDRED
0377 116400	ADJUST2:	LXI	D,0064H
037A 19	;	DAD	D
037B 79	;	MOV	A,C
037C 325500	;	STA	BUFFLOC+1
037F 7D	;	MOV	A,L
0380 0E00	;	MVI	C,00H
0382 FE0A	TENS:	CPI	0AH
0384 FA8A03	;	JM	ZEROS
0387 0C	;	INR	C
		SUT	0AH

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364

SOURCE FILE NAME: VLCRQI.ASM

038A 325700	ZEROS:	STA	BUFFLOC+3
	;	MOV	A,C
038D 79	;	STA	BUFFLOC+2
038E 325600	;	LXI	D,BUFFLOC
0391 115400	;	LXI	H,LOOK_TAB
0394 214A00	;	MVI	C,04H
0397 0E04	;	PUSH	H
0399 E5	CNVRT:	LDAX	D
039A 1A	;	ADD	L
039B 85	;	MOV	L,A
039C 6F	;	MOV	A,M
039D 7E	;	STAX	D
039E 12	;	INX	D
039F 13	;	POP	H
03A0 E1	;	DCR	C
03A1 0D	;	JNZ	CNVRT
03A2 C29903	;	RET	
03A5 C9	;	MVI	B,02H
03A6 0602	UNITDSP:	LXI	H,BUFFLOC+4
03A8 215800	;	XCHG	
03AB EB	AGAIN:	MOV	A,M
03AC 7E	;	XCHG	
03AD EB	;	MOV	M,A
03AE 77	;	INX	D
03AF 13	;	10X	H
	;	DCR	B

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364

SOURCE FILE NAME: VLCRQI.ASM

03B2 C2AB03	;	JNZ	AGAIN
03B5 C9		RET	
03B6 3E90	BUFFOUT:	MVI	A,90H
03B8 D319	;	OUT	CTRLPRT8
03BA 0606	;	MVI	B,06H
03BC 215400	;	LXI	H,BUFFLOC
03BF 7E	NEXT:	MOV	A,M
03C0 D318	;	OUT	CTRLPRT9
03C2 23	;	INX	H
03C3 05	;	DCR	B
03C4 C2BF03	;	JNZ	NEXT
03C7 C9	;	RET	

---

;C_MEASUREMENT STARTS			
03C8 3E04	CMEASURE:	MVI	A,CMEASLED
03CA D322	;	OUT	CTRLPRT4
03CC 3E00	START2:	MVI	A,00H
03CE 325B00	;	STA	DFALTLOC
03D1 3E04	;	MVI	A,04H
03D3 325C00	;	STA	DFALTLOC+1
03D6 3E08	;	MVI	A,08H
03D8 325D00	;	STA	DFALTLOC+2
03DB 3E14	;	MVI	A,14H
03DD 325E00	;	STA	DFALTLOC+3
		MVI	A,EMT_HLP
		OUT	CTRLPRT2

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364  
 SOURCE FILE NAME: VLCRQI.ASM

03E4 DB19	;	RDKBRD1:	IN	CTRLPRT8
03E6 E601	;		ANI	01H
03E8 3E40	;		MVI	A,40H
03EA D319	;		OUT	CTRLPRT8
03EC DB18	;		IN	CTRLPRT9
03EE E63F	;		ANI	3FH
03F0 FE09	;		CPI	<u>KEY_9</u>
03F2 CA1A04	;		JZ	PULLUP1
03F5 FEOF	;		CPI	<u>KEY_11</u>
03F7 CA1504	;		JZ	SAVE1
03FA FEOC	;		CPI	<u>KEY_12</u>
03FC CA1504	;		JZ	SAVE1
03FF FEOF	;		CPI	<u>KEY_15</u>
0401 CA1504	;		JZ	SAVE1
0404 FE0D	;		CPI	<u>KEY_13</u>
0406 CA1504	;		JZ	SAVE1
0409 FEOE	;		CPI	<u>KEY_14</u>
040B CA1504	;		JZ	SAVE1
040E 3E04	;		MVI	A,PARAERR_
0410 D320	;		OUT	CTRLPRT3
0412 C3E403	;		JMP	RDKBRD1
0415 D60B	SAVE1:		SUI	0BH
0417 325B00	;		STA	DFALTLOC
	;		MVI	A,ERRCLR_
	PULLUP1:		OUT	CTRLPRT3

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364  
 SOURCE FILE NAME: VLCRQI.ASM

041E 3E01	;	MVI	A, ENT_HLP
0420 D321	;	OUT	CTRLPRT2
0422 DB19	RDKBRD2:	IN	CTRLPRT8
0424 E601	;	ANI	01H
0426 CA2204	;	JZ	RDKBRD2
0429 3E40	;	MVI	A, 40H
042B D319	;	OUT	CTRLPRT8
042D DB18	;	IN	CTRLPRT9
042F E63F	;	ANI	3FH
0431 FE09	;	CPI	KEY_9
0433 CA3D04	;	JZ	AGAIN1
0436 3E02	;	MVI	A, ENTERR_
0438 D320	;	OUT	CTRLPRT3
043A C32204	;	JMP	RDKBRD2
043D 3E00	AGAIN1:	MVI	A, ERRCLR_
043F D320	;	OUT	CTRLPRT3
0441 3E02	;	MVI	A, PARA_HLP
0443 D321	;	OUT	CTRLPRT2
0445 DB19	RDKBRD3:	IN	CTRLPRT8
0447 E601	;	ANI	01H
0449 CA4504	;	JZ	RDKBRD3
044C 3E40	;	MVI	A, 40H
044E D319	;	OUT	CTRLPRT8
0450 DB18	;	IN	CTRLPRT9
		ANI	3FH
		CPI	KEY_9

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364  
 SOURCE FILE NAME: VLQRQI.ASM

0456 CA8804	;	JZ	PULLUP2
0459 FE0B	;	CPI	<u>KEY_11</u>
045B CA7704	;	JZ	SAVE2
045E FE0C	;	CPI	<u>KEY_12</u>
0460 CA7704	;	JZ	SAVE2
0463 CA7704	;	JZ	SAVE2
0466 FE0E	;	CPI	<u>KEY_14</u>
0468 CA7704	;	JZ	SAVE2
046B FEOF	;	CPI	<u>KEY_15</u>
046D CA7704	;	JZ	SAVE2
0470 3E04	;	MVI	A, PARAERR_
0472 D320	;	OUT	CTRLPRT3
0474 C34504	;	JMP	RDKBRD3
0477 D60B	SAVE2:	SUI	0BH
0479 4F	;	MOV	C,A
047A 3A5B00	;	LDA	DFALTLOC
047D B9	;	CMP	C
047E FA8404	;	JM	NEXT1
0481 C3CC03	;	JMP	START2
0484 79	NEXT1:	MOV	A,C
0485 325C00	;	STA	DFALTLOC+1
0488 3E00	PULLUP2:	MVI	A, ERRCLR_
048A D320	;	OUT	CTRLPRT3
	;	MVI	A, ENT_HLP
	;	OUT	CTRLPRT2

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364  
 SOURCE FILE NAME: VLCRQI.ASM

0490 DB19	RDKBRD4:	IN	CTRLPRT8
0492 E601	;	ANI	01H
0494 CA9004	;	JZ	RDKBRD4
0497 3E40	;	MVI	A,40H
0499 D319	;	OUT	CTRLPRT8
049B DB18	;	IN	CTRLPRT9
049D E63F	;	ANI	3FH
049F FE09	;	CPI	<u>KEY_9</u>
04A1 CAAB04	;	JZ	AGAIN2
04A4 3E02	;	MVI	A,ENTER <sub>—</sub>
04A6 D320	;	OUT	CTRLPRT3
04A8 C39004	;	JMP	RDKBRD4
04AB 3E00	AGAIN2:	MVI	A,ERRCLR <sub>—</sub>
04AD D320	;	OUT	CTRLPRT3
04AF 3E02	;	MVI	A,PARA_HLP
04B1 D321	;	OUT	CTRLPRT2
04B3 DB19	RDKBRD5:	IN	CTRLPRT8
04B5 E601	;	ANI	01H
04B7 CAB304	;	JZ	RDKBRD5
04BA 3E40	;	MVI	A,40H
04BC D319	;	OUT	CTRLPRT8
04BE DB18	;	IN	CTRLPRT9
04C0 E63F	;	ANI	3FH
04C2 FE09	;	CPI	<u>KEY_9</u>
		JZ	PULLUP <sub>3</sub>
		CPI	<u>KEY-16</u>

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364  
 SOURCE FILE NAME: VLCRQI.ASM

04C9 CA0000	;	JZ	SAVE3
04CC FE11	;	CPI	KEY_17
04CE CAEC04	;	JZ	SAVE4
04D1 FE00	;	CPI	KEY_18
04D3 CAFD04	;	JZ	SAVE5
04D6 3E04	;	MVI	A, PARAERR_
04D8 D320	;	OUT	CTRLPRT3
04DA C3B304	;	JMP	RDKBRD5
04DD D303	;	OUT	CTRLPRT3
04DF 3E08	;	MVI	A, WIDTH_1
04E1 325D00	;	STA	DFALTLOC+2
04E4 3E14	;	MVI	A, DCRCNT_1
04E6 328600	;	STA	DFALTLOC+43
04E9 C30B05	;	JMP	PULLUP3
04EC 3E00	SAVE4:	MVI	A, ERRCLR_
04EE D320	;	OUT	CTRLPRT3
04F0 3E11	;	MVI	A, WIDTH_2
04F2 325D00	;	STA	DFALTLOC+2
04F5 3E0A	;	MVI	A, DCRCNT_2
04F7 325E00	;	STA	DFALTLOC+3
04FA C30B05	;	JMP	PULLUP3
04FD 3E00	SAVE5:	MVI	A, ERRCLR_
04FF D320	;	OUT	CTRLPRT3
	;	MVI	A, WIDTH_3
	;	STA	DFALTLOC+2

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364  
 SOURCE FILE NAME: VLCRQI.ASM

0506 3E05	;	MVI	A,DCRCNT_3
0508 325E00	;	STA	DFALTLOC+3
050B 3E01	PULLUP3:	MVI	A,ENT_HLP
050D D321	;	OUT	CTRLPRT2
050F DB19	RDKBRD6:	IN	CTRLPRT8
0511 E601	;	ANI	01H
0513 CA0F05	;	JZ	RDKBRD6
0516 3E40	;	MVI	A,40H
0518 D319	;	OUT	CTRLPRT8
051A E63F	;	ANI	3FH
051C FE09	;	CPI	KEY_9
051E CA2805	;	JZ	CSTART
0521 3E02	;	MVI	A,ENTERR_
0523 D320	;	OUT	CTRLPRT3
0525 C30F05	;	JMP	RDKBRD6
0528 3E00	CSTART:	MVI	A,ERRCLR_
052A D320	;	OUT	CTRLPRT3
052C 3E03	;	MVI	A,C_SELECT
052E D326	;	OUT	CTRLPRT1
0530 3A5E00	;	LDA	DFALTLOC+3
0533 325600	;	STA	TEMPLOC+2
0536 3A5D00	ROUND:	LDA	DFALTLOC+2
0539 325700	;	STA	TEMPLOC+3
		LXI	H,BADDE_C

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364  
 SOURCE FILE NAME: VLCRQI.ASM

053F 3A5B00		LDA	DFALTLOC
;			
0542 87	;	ADD	A
;			
0543 85	;	ADD	L
;			
0544 6F	;	MOV	L,A
;			
0545 7E	;	MOV	A,M
;			
0546 325400	;	STA	TEMPLOC
;			
0549 23	;	INX	H
;			
054A 7E	;	MOV	A,M
;			
054B 325500	;	STA	TEMPLOC+1
;			
054E 1EB4	;	MVI	E,0B4H
;			
0550 3A5400	;	LDA	TEMPLOC
;			
0553 57	;	MOV	D,A
;			
0554 215600	REPEAT:	LXI	H,TEMPLOC+2
;			
0557 7B	;	MOV	A,E
;			
0558 96	;	SUB	M
;			
0559 5F	;	MOV	E,A
;			
055A 3A5700	;	LDA	TEMPLOC+3
;			
055D 3D	;	DCR	A
;			
055E 325700	;	STA	TEMPLOC+3
;			
0561 7B	;	MOV	A,E
;			
0562 D324	;	OUT	CTRLPRT6
;			
0564 212A00	CONT3:	LXI	H,CRNGCWRD
;			
0567 7A	;	MOV	A,D
;			
0568 85	;	ADD	L
;			
		MOV	L,A
		MOV	A,M

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364  
 SOURCE FILE NAME: VLCRQI.ASM

056B D300	;	OUT	CTRLPRTC
056D DB28	;	IN	CTRLPRTB
056F 4F	;	MOV	C,A
0570 DB27	;	IN	CTRLPRTA
0572 47	;	MOV	B,A
0573 E610	;	ANI	10H
0575 CA8A05	;	JZ	CONT1
0578 3A5400	;	LDA	TEMPLOC
057B BA	;	CMP	D
057C C28605	;	JNZ	CONT2
057F 3E01	;	MVI	A, OVRERR
0581 D320	;	OUT	CTRLPRT3
0583 C35405	;	JMP	REPEAT
0586 15	CONT2:	DCR	D
0587 C36405	;	JMP	CONT3
058A 78	CONT1:	MOV	A,B
058B E60F	;	ANI	0FH
058D CA9E05	;	JZ	CONT4
0590 FE01	;	CPI	01H
0592 C29B05	;	JNZ	CONT5
0595 79	;	MOV	A,C
0596 FE90	;	CPI	90H
0598 FA9E05	;	JM	CONT4
059B C3B105	CONT5:	JMP	DISPLAY
	;	LDA	TEMPLOC + 1
	CONT4:	CMP	D

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364  
 SOURCE FILE NAME: VLCRQI.ASM

05A2 C2AC05	;	JNZ	CONT6
05A5 3E01	;	MVI	A, OVRERR
05A7 D320	;	OUT	CTRLPRT3
05A9 C30706	;	JMP	SETFRNG
05AC 7A	CONT6:	MOV	A, D
05AD 14	;	INR	D
05AE C36405	;	JMP	CONT3
05B1 78	DISPLAY:	MOV	A, B
05B2 E60F	;	ANI	OFH
05B4 325A00	;	STA	TEMPLOC+6
05B7 79	;	MOV	A, C
05B8 325900	;	STA	TEMPLOC+5
05BB CD1606	;	CALL	CDSPLY
05BE DB19	RDENT1:	IN	CTRLPRT8
05C0 E601	;	ANI	01H
05C2 CABE05	;	JZ	RDENT1
05C5 3E40	;	MVI	A, 40H
05C7 D319	;	OUT	CTRLPRT8
05C9 DB18	;	IN	CTRLPRT9
05CB E63F	;	ANI	3FH
05CD FE09	;	CPI	KEY_9
05CF C2BE05	;	JNZ	RDENT1
05D2 CDBD06	;	CALL	FDSPLY
05D5 DB19	RDENT2	IN	CTRLPRT8
		ANI	01H

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364  
 SOURCE FILE NAME: VLCRQI.ASM

05D9 CAD505	;	JZ	RDENT2
05DC 3E40	;	MVI	A,40H
05DE D319	;	OUT	CTRLPRT8
05E0 DB18	;	IN	CTRLPRT9
05E2 E63F	;	ANI	3FH
05E4 FE09	;	CPI	KEY_9
05E6 C2D505	;	JNZ	RDENT2
05E9 CD1407	;	CALL	TDDSPLY
05EC DB19	RDENT3:	IN	CTRLPRT8
05EE E601	;	ANI	01H
05F0 CAEC05	;	JZ	RDENT3
05F3 3E40	;	MVI	A,40H
05F5 D319	;	OUT	CTRLPRT8
05F7 DB18	;	IN	CTRLPRT9
05F9 E63F	;	ANI	3FH
05FB FE09	;	CPI	KEY_9
05FD 3A5700	;	LDA	TEMPLOC+3
0600 3D	;	DCR	A
0601 325700	;	STA	TEMPLOC+3
0604 C25405	;	JNZ	REPEAT
0607	SETFRNG :	LDA	DFALTLOC
0607 3C	;	INR	A
0608 325B00	;	STA	DFALTLOC
060B 47	;	MOV	B,A
		LDA	DFALTLOC+1

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364

SOURCE FILE NAME: VLCRQI.ASM

060F B8	CMP	B
0610 FA3605	JM	ROUND
0613 C3EE00	JMP	START
0616 E5 CDSPLY:	PUSH	H
0617 D5	PUSH	D
0618 2A5900	LHLD	TEMPLOC+5
061B EB	XCHG	
061C 215400	LXI	H,BADDRROM
061F 19	DAD	D
0620 19	DAD	D
0621 115400	LXI	D,BUFFLOC
0624 7E	MOV	A,M
0625 E60F	ANI	OFH
0627 12	STAX	D
0628 13	INX	D
0629 7E	MOV	A,M
062A E6F0	ANI	OFOH
062C 12	STAX	D
062D 23	INX	H
062E 13	INX	D
062F 7E	MOV	A,M
0630 E60F	ANI	OFH
0632 12	STAX	D
0633 13	INX	D
0634 7E	MOV	A,M
	ANI	OFOH

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364  
 SOURCE FILE NAME: VLCRQI.ASM

0637 12	;	STAX	D
0638 CD3607	;	CALL	SEGCVRT
063B D1	;	POP	D
063C D5	;	PUSH	D
063D 3A5B00	;	LDA	DFALTLOC
0640 47	;	MOV	B,A
0641 04	;	INR	B
0642 0E06	;	MVI	C,06H
0644 3E56	;	MVI	A,CMPLMNT3
0646 81	TRACK:	ADD	C
0647 05	;	DCR	B
0648 C24606	;	JNZ	TRACK
064B 47	;	MOV	B,A
064C 7A	;	MOV	A,D
064D 90	;	SUB	B
064E FE00	;	CPI	00H
0650 CA6A06	;	JZ	CUNIT1
0653 FE01	;	CPI	01H
0655 CA7306	;	JZ	CUNIT2
0658 CA7C06	;	JZ	CUNIT3
065B FE03	;	CPI	03H
065D CA8506	;	JZ	CUNIT4
0660 FE04	;	CPI	04H
0662 CA8E06	;	JZ	CUNIT5
		CPI	05H

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364

SOURCE FILE NAME: VLCRQI.ASM

0667 CA9706		JZ	CUNIT6
066A 116900	CUNIT1:	LXI	D,CRNG1
066D 215500	;	LXI	H,BUFFLOC+1
0670 C3A006	;	JMP	ACTION1
0673 116D00	CUNIT2:	LXI	D,CRNG2
0676 215400	;	LXI	H,BUFFLOC
0679 C3A006	;	JMP	ACTION1
067C 116D00	CUNIT3	LXI	D,CRNG2
067F 215600	;	LXI	H,BUFFLOC+2
0682 C3A006	;	JMP	ACTION1
0685 116D00	CUNIT4:	LXI	D,CRNG2
0688 215500	;	LXI	H,BUFFLOC+1
068B C3A006	;	JMP	ACTION1
068E 116D00	CUNIT5:	LXI	D,CRNG2
0691 215400	;	LXI	H,BUFFLOC
0694 C3A006	;	JMP	ACTION1
0697 117100	CUNIT6:	LXI	D,CRNG3
069A 215600	;	LXI	H,BUFFLOC+2
069D C3A006	;	JMP	ACTION1
06A0 3E01	ACTION1:	MVI	A,01H
06A2 B6	;	ORA	M
06A3 77	;	MOV	M,A
06A4 CDAD06	;	CALL	UNITDSP1
06A7 CDB603	;	CALL	BUFFOUT
06AA D1	;	POP	D
		POP	H

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364  
 SOURCE FILE NAME: VLCRQI.ASM

06AC C9		RET
06AD 0604	UNITDSP1:	MVI B,04H
06AF 215800	;	LXI H,BUFFLOC+4
06B2 EB	AGAIN3:	XCHG
06B3 7E	;	MOV A,M
06B4 EB	;	XCHG
06B5 77	;	MOV M,A
06B6 13	;	INX D
06B7 23	;	INX H
06B8 05	;	DCR B
06B9 C2B206	;	JNZ AGAIN3
06BC C9	;	RET
06BD E5	FDSPLY:	PUSH H
06BE D5	;	PUSH D
06BF 215400	;	LXI H,BUFFLOC
06C2 3A5B00	;	LDA DFALTLOC
06C5 47	;	MOV B,A
06C6 E6F0	;	ANI 0FOH
06C8 77	;	MOV M,A
06C9 23	;	INX H
06CA 78	;	MOV A,B
06CB E60F	;	ANI OFH
06CD 23	;	INX H
06CE 3A5700	;	LDA TEMPLOC+3
		MOV B,A

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364  
 SOURCE FILE NAME: VLCROI.ASM

06D2 E6F0		ANI	0FOH
06D4 77	;	MOV	M,A
06D5 23	;	INX	H
06D6 78	;	MOV	A,B
06D7 E60F	;	ANI	0FH
06D9 77	;	MOV	M,A
06DA 3A5600	;	LDA	TEMPLOC+2
06DD 23	;	INX	H
06DE FE05	;	CPI	05H
06E0 C27A02	;	JNZ	AHEAD1
06E3 3E00	;	MVI	A,SEGCOD00
06E5 77	;	MOV	M,A
06E6 23	;	INX	H
06E7 3E00	;	MVI	A,SEGCOD01
06E9 77	;	MOV	M,A
06EA C30307	;	JMP	LASTFILD
06ED FE0A	AHEAD1:	CPI	0AH
06EF C2FC06	;	JNZ	AHEAD2
06F2 3E00	;	MVI	A,SEGCOD10
06F4 77	;	MOV	M,A
06F5 23	;	INX	H
06F6 3E00	;	MVI	A,SEGCOD11
06F8 77	;	MOV	M,A
06F9 C30307	;	JMP	LASTFILD
06FC 3E00	AHEAD2:	MVI	A,SEGCOD20
		MOV	M,A

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364  
 SOURCE FILE NAME: VLCRQI.ASM

06FF 23		INX	H
0700 3E00	;	MVI	A, SEGCOD21
0702 77	;	MOV	M, A
0703 3E00	LASTFILD:	MVI	A, SEGCODF1
0705 23	;	INX	H
0706 77	;	MOV	M, A
0707 23	;	INX	H
0708 3E00	;	MVI	A, SEGCODF2
070A 77	;	MOV	M, A
070B CD3607	;	CALL	SEGCNVRT
070E CDB603	;	CALL	BUFFOUT
0711 D1	;	POP	D
0712 E1	;	POP	H
0713 C9	;	RET	
	TDMEASUREMENT		
0714 E5	TDDSPLY:	PUSH	H
0715 D5	;	PUSH	D
0716 3E04	;	MVI	A, TDSELECT
0718 D326	;	OUT	CTRLPRT1
071A DB27	;	IN	CTRLPRTA
071C 325A00	;	STA	TEMPLOC+6
071F DB28	;	IN	CTRLPRTB
0721 E60F	;	ANI	OFH
0723 325900	;	STA	TEMPLOC+5
	;	CALL	BCDCNVRT

AVOCET SYSTEMS 8085/Z80 ASSEMBLER - VERSION 1.05M SERIAL #00364

SOURCE FILE NAME: VLCRQI.ASM

0729 CDAD06	;	CALL	UNITDSP1
072C CDB603	;	CALL	BUFFOUT
072F 3E03	;	MVI	A,C_SELECT
0731 D326	;	OUT	CTRLPRT1
0733 D1	;	POP	D
0734 E1	;	POP	H
0735 C9	;	RET	
0736 115400	SEGCNVRT:	LXI	D,BUFFLOC
0739 214A00	;	LXI	H,LOOK_TAB
073C 0E02	;	MVI	C,02H
073E E5	CNVRT1:	PUSH	H
073F 1A	;	LDAX	D
0740 85	;	ADD	L
0741 6F	;	MOV	L,A
0742 7E	;	MOV	A,M
0743 12	;	STAX	D
0744 13	;	INX	D
0745 E1	;	POP	H
0746 0D	;	DCR	C
0747 C23E07	;	JNZ	CNVRT1
074A C9	;	RET	
<hr/>			
0000		END ;This stmt inserted by assembler	