

CHAPTER : 1

PRELIMINARIES

1.1 INTRODUCTION :

One of the desirable properties of a good estimator is that as the number of observations increases the estimator should come closer and closer in some sense, to the true value of the unknown parameter.

A sequence of estimators $\{T_n\}$ for a parametric function $g(\theta)$ is "Consistent" if T_n converges to $g(\theta)$ in some appropriate sense. As T_n is a random variable, one of the possible way to explain the above property of a sequence of estimators is as $n \rightarrow \infty$, $|T_n - \theta| \rightarrow 0$ in some mode of convergence. If this mode of convergence is in probability then T_n is said to be weak consistent, that is let X_1, X_2, \dots, X_n be a random sample from a distribution $F(\cdot, \theta)$, $\theta \in \Theta$ (θ un-known) then an estimator $T_n = T(X_1, X_2, \dots, X_n)$ of θ is called consistent if for every $\epsilon > 0$,

$$\lim_{n \rightarrow \infty} P_{\theta, n} \{ |T_n - \theta| \geq \epsilon \} = 0, \quad \forall \theta \in \Theta \quad (1.1.1)$$

Example : 1.1.1: Let X_1, X_2, \dots, X_n be independent identically distributed (i.i.d.) random variables from normal mean θ and variance one, $T_n = \bar{X}_n$.

Note that $\bar{X} \rightarrow N(\theta, \frac{1}{n})$ hence

$$\begin{aligned}
 P_{\theta, n} [| \bar{X}_n - \theta | \geq \epsilon] &= P_{\theta, n} [| \frac{\bar{X}_n - \theta}{1/\sqrt{n}} | \geq \sqrt{n} \epsilon] \\
 &= 2 [1 - \Phi (\sqrt{n} \epsilon)] \rightarrow 0
 \end{aligned}$$

as $n \rightarrow \infty$. Hence T_n is consistent estimator for θ .

Example : 1.1.2 : Let X_1, X_2, \dots, X_n be i.i.d. r.v.'s with uniform distribution on $(0, \theta)$. We shall see consistency of T_n where $T_n = \max (X_1, X_2, \dots, X_n)$. We know here that the probability density function (p.d.f.) of T_n is

$$\begin{aligned}
 f_n(t) &= \frac{n!}{(n-1)!(n-n)!} (t/\theta)^{n-1} (1 - t/\theta)^{n-n} \times f_n(t) \frac{1}{\theta} \\
 &= \frac{n t^{n-1}}{\theta^n}, \quad 0 < t < \theta.
 \end{aligned}$$

$$\begin{aligned}
 \text{Consider } P [| T_n - \theta | \geq \epsilon] &= P_{\theta} [T_n < \theta - \epsilon] \\
 &= P_{\theta} [X_{(n)} < \theta - \epsilon] = 0, \\
 &\hspace{15em} \text{if } \epsilon > \theta.
 \end{aligned}$$

$$\begin{aligned}
 \text{For } \epsilon \leq \theta ; \quad P_{\theta} [X_{(n)} < \theta - \epsilon] \\
 &= \int_0^{\theta - \epsilon} \frac{n t^{n-1}}{\theta^n} dt \\
 &= \frac{n}{\theta^n} \left[\frac{t}{n} \right]_0^{\theta - \epsilon} \\
 &= \left(1 - \frac{\epsilon}{\theta} \right)^n \rightarrow 0, \quad \text{as } n \rightarrow \infty.
 \end{aligned}$$

Thus T_n is consistent for θ .

Example : 1.1.3 : Let $\{X_1, X_2, \dots, X_n\}$ be a sequence of random variable with marginal distribution function $F(x, \theta)$ and $P [X_i = X_1] = 1, \forall i = 1, 2, 3, \dots$

In this case note that for any sample point (X_1, X_2, \dots, X_n) , $T_n (X_1, X_2, \dots, X_n) = S(X_1)$ then as we know that

$$\begin{aligned} P_{\theta} [| T_n - \theta | \geq \epsilon] \\ = P_{\theta} [| S(X_1) - \theta | \geq \epsilon] \not\rightarrow 0, \\ \text{as } n \rightarrow \infty \forall \theta \in \Theta, \end{aligned}$$

provided $S(X_1)$ is not equal to zero with probability one. Thus $T_n = S(X_1)$ is not consistent estimator for θ .

1.2 PROPERTIES OF CONSISTENT ESTIMATORS :

In the following we discuss some properties of consistent estimators

1.2.1 : Consistent estimator need not be unique. Note that if T_n is consistent for $g(\theta)$ then $T_n + \frac{1}{n}$ is also consistent for $g(\theta)$.

Example : 1.2.1 : Let X_1, X_2, \dots, X_n be i.i.d. r.v's with $U(0, \theta)$, $\theta \in (0, \infty)$. We define $T_1 = X_{(n)}$ and $T_2 = 2\tilde{X}_m$ where $\tilde{X}_m = \text{median}$, are consistent for θ .

consider

$$\begin{aligned}
 P_{\theta} [| T_2 - \theta | > \epsilon] &= P_{\theta} [| 2\tilde{X}_m - \theta | > \epsilon] \\
 &= 1 - P_{\theta} [\frac{\theta - \epsilon}{2} \leq \tilde{X}_m \leq \frac{\theta + \epsilon}{2}] \\
 &= 1 - \int_{\frac{\theta - \epsilon}{2}}^{\frac{\theta + \epsilon}{2}} \frac{n!}{(\frac{n-1}{2})! (\frac{n-1}{2})!} \frac{1}{\theta^n} (X)^{\frac{n-1}{2}} (x-\theta)^{\frac{n-1}{2}} dx \\
 &= 2 \int_0^{\frac{\theta - \epsilon}{2}} \frac{1}{\beta(\frac{n+1}{2}, \frac{n+1}{2})} \frac{1}{\theta^n} x^{\frac{n-1}{2}} (x - \theta)^{\frac{n-1}{2}} dx. \\
 &\leq \frac{2}{\theta^n} (\frac{\theta - \epsilon}{2}) (\frac{\theta - \epsilon}{2})^{\frac{n-1}{2}} (\frac{\theta + \epsilon}{2})^{\frac{n-1}{2}} \frac{1}{\beta(\frac{n+1}{2}, \frac{n+1}{2})} \\
 &= (\frac{\theta - \epsilon}{\theta}) (\frac{1}{2})^{n-1} (\frac{\theta^2 - \epsilon^2}{\theta^2})^{\frac{n-1}{2}} \frac{1}{\beta(\frac{n+1}{2}, \frac{n+1}{2})} \quad (1.2.1)
 \end{aligned}$$

Now consider $\beta(\frac{n+1}{2}, \frac{n+1}{2}) = \frac{\Gamma(\frac{n+1}{2}) \Gamma(\frac{n+1}{2})}{\Gamma(n+1)}$

$$= \frac{(\frac{n-1}{2})! (\frac{n-1}{2})!}{n!}$$

By using stirling's approximation we have

$$\begin{aligned}
 \beta(\frac{n+1}{2}, \frac{n+1}{2}) &= \frac{e^{-(n-1)} \left[(\frac{n-1}{2})^{\frac{n-1}{2} + \frac{1}{2}} \right]^2 \sqrt{2\pi}}{e^{-n} n^{n+1/2}} \\
 &= \frac{\sqrt{2\pi}}{e} (\frac{n-1}{2})^n \frac{1}{n^{n+1/2}} \\
 &= \frac{\sqrt{2\pi}}{e} \cdot \frac{1}{2^n} \cdot (\frac{n-1}{n})^n \cdot \frac{1}{\sqrt{n}}
 \end{aligned}$$

$$\begin{aligned}
 &= \frac{\sqrt{2\pi}}{\theta} \cdot \frac{1}{2^n} \cdot \left(1 - \frac{1}{n}\right)^n \cdot \frac{1}{\sqrt{n}} \\
 &= \frac{\sqrt{2\pi}}{\theta} \cdot \frac{1}{2^n \sqrt{n}} \tag{1.2.2}
 \end{aligned}$$

from (1.2.1) and (1.2.2) we have

$$\begin{aligned}
 P_\theta \left[|2 \tilde{X}_m - \theta| > \varepsilon \right] &\leq \left(\frac{\theta - \varepsilon}{\theta}\right) \frac{2 \cdot \theta^2}{\sqrt{2 \cdot \pi}} \left(1 - \frac{\varepsilon^2}{\theta^2}\right)^{\frac{n-1}{2}} \sqrt{n} \\
 &\longrightarrow 0, \text{ as } n \longrightarrow \infty.
 \end{aligned}$$

Hence $P_\theta \left[|2 \tilde{X}_m - \theta| > \varepsilon \right] \longrightarrow 0, \text{ as } n \longrightarrow \infty.$

Thus $2 \tilde{X}_m$ is consistent for θ , similarly from example 1.1.2.

$T_1 = X_{(n)}$ is consistent for θ .

1.2.2 : Unbiased estimator need not be consistent and viceversa.

Example : 1.2.2 : Let X_1, X_2, \dots, X_n be i.i.d. r.v.'s with $N(\theta, 1)$. Define $T_n = X_1, \forall n$.

Here $E_\theta(T_n) = E_\theta(X_1) = \theta, \forall \theta \in \theta$

Consider $P_\theta \left[|T_n - \theta| \geq \varepsilon \right] = P_\theta \left[|X_1 - \theta| \geq \varepsilon \right] \not\rightarrow 0$

This implies that T_n is not consistent.

Example : 1.2.3 : Let X_1, X_2, \dots, X_n be i.i.d. r.v.'s with

$lu(0, \theta)$. Here we know that $T_n = X_{(n)}$ is consistent

estimator for θ but $E_\theta(T_n) = \frac{n}{n+1} \theta$.

Thus T_n is not unbiased. Hence consistent estimator need not be unbiased.

1.2.3 : Sample mean is consistent for population mean.

For reference we define weak law of large numbers (WLLN)

(Bhat (1985) P.193)

Let X_n be a sequence of random variables and let

$S_n = \sum_{k=1}^n X_k$; $n = 1, 2, \dots$ we say that $\{X_n\}$ obeys the WLLN

with respect to the sequence of constants $\{B_n\}$; $B_n > 0$,

$B_n \uparrow \infty$, if there exist a sequence of real constants A_n such that

$$B_n^{-1} (S_n - A_n) \xrightarrow{P} 0, \text{ as } n \longrightarrow \infty$$

A_n is called centring constants and B_n is norming constants.

Let X_1, X_2, \dots, X_n be a random sample from $f(\cdot)$.

If $S_n = \sum_{i=1}^n X_i$, $A_n = ES_n = nEX_1$ and $B_n = n$ then by WLLN

$$n^{-1}(S_n - nE(X_1)) \xrightarrow{P} 0, \text{ as } n \longrightarrow \infty.$$

This can be proved by Theorem 1 (pp 257 Rohatgi(1986)).

Thus $\frac{S_n}{n} \xrightarrow{P} E(X_1)$, that is sample mean is consistent for population mean.

1.2.4 : If T_{1n} is consistent for $g_1(\theta)$ and T_{2n} is consistent for $g_2(\theta)$ then,

a) $(T_{1n} \pm T_{2n})$ is consistent for $(g_1(\theta) \pm g_2(\theta))$

b) $(T_{1n} T_{2n})$ is consistent for $(g_1(\theta) g_2(\theta))$

c) $\frac{T_{1n}}{T_{2n}}$ is consistent for $\frac{g_1(\theta)}{g_2(\theta)}$ provided that

T_{2n} is not zero for every n and $g_2(\theta)$ is also not zero.

Above properties of two consistent estimators can be proved by Theorem 6.1 (P.108 Bhat (1985)).

1.2.5 : For reference the definition of central limit theorem is given below. (P.69 Zacks (1981)).

If $\{X_n\}$ is a sequence of i.i.d. random variables having a finite variance σ^2 , $0 < \sigma^2 < \infty$ and if

$E(X) = \mu$ then,

$$\lim_{n \rightarrow \infty} P\left[\sqrt{n} (\bar{X}_n - \mu) \leq \sigma \cdot \epsilon\right] = \Phi(\epsilon)$$

where $\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$.

1.2.6 : Consistency is preserved under continuous transformation or function, that is let T_n be consistent estimator for θ and if g is continuous function on Θ , then $g(T_n)$ is consistent for $g(\theta)$.

Proof for this property will be as following.

Fix θ say $\theta = \theta_0$ and g is continuous at θ_0 , then $\forall \epsilon > 0$ there exist a $\delta > 0$ such that

$$|g(\theta) - g(\theta_0)| < \epsilon \text{ whenever } |\theta - \theta_0| < \delta.$$

So for every $\epsilon > 0$ there exist a $\delta > 0$ such that

$$[|\theta - \theta_0| < \delta] \subset [|g(\theta) - g(\theta_0)| < \epsilon] \quad (1.2.5)$$

We know that T_n is consistent for θ , then for every

$$r > 0, \quad P_{\theta_0} \{ |T_n - \theta_0| > r \} \longrightarrow 0, \text{ as } n \longrightarrow \infty$$

$$\text{or } P_{\theta_0} \{ |T_n - \theta_0| \leq r \} \longrightarrow 1, \text{ as } n \longrightarrow \infty. \quad (1.2.6)$$

Then from (1.2.5) and (1.2.6) we get for every $\epsilon > 0$,

$$P_{\theta_0} \{ |g(T_n) - g(\theta_0)| \leq \epsilon \} \geq P_{\theta_0} \{ |T_n - \theta_0| \leq r \} \\ \longrightarrow 1, \text{ as } n \longrightarrow \infty.$$

$$\Rightarrow \lim_{n \rightarrow \infty} P_{\theta} \{ |g(T_n) - g(\theta_0)| \leq \epsilon \} \geq 1.$$

Thus $1 \geq \lim_{n \rightarrow \infty} P_{\theta_0} \{ |g(T_n) - g(\theta_0)| \leq \epsilon \} \geq 1$ Hence $g(T_n)$ is consistent for $g(\theta_0)$.

Example : 1.2.5 : Let X_1, X_2, \dots, X_n be i.i.d. random variables with density

$$f_x(x, \theta) = \begin{cases} \frac{1}{\theta} e^{-x/\theta} & x \geq 0, \theta > 0 \\ 0 & \text{otherwise.} \end{cases}$$

$$\text{Consider } g(\theta) = \begin{cases} 1 & \text{if } \theta > 2 \\ 0 & \text{otherwise.} \end{cases}$$

Here g is not continuous at $\theta = 2$ and let $T_n = \bar{X}$ which is consistent estimator for θ . We shall examine the consistency of $g(T_n)$ for $g(\theta)$.

Let $\theta_0 > 0$ be fixed.

Case I : Suppose that $\theta_0 > 2$, then $g(\theta)$ is continuous at θ_0 .

$$\text{So } g(\theta_0^+) = \lim_{\substack{n \rightarrow \infty \\ h \rightarrow 0}} g(\theta_0 + h) = 1$$

$$g(\theta_0^-) = \lim_{\substack{n \rightarrow \infty \\ h \rightarrow 0}} g(\theta_0 - h) = 1$$

Note that $\theta_0 - h$ satisfies inequality

$$2 < \theta_0 - h < \theta_0, \quad \text{if } h < \theta_0 - 2$$

$$\text{So } g(\theta_0 - h) = \begin{cases} 1 & \text{if } h < \theta_0 - 2 \\ 0 & \text{otherwise} \end{cases}$$

$$\begin{aligned} \text{Consider now } & P_{\theta} \{ |g(T_n) - g(\theta)| < \epsilon \} \\ &= P_{\theta} \{ |g(T_n) - 1| < \epsilon \} \\ &= P_{\theta} \{ T_n > 2 \} \\ &= P_{\theta} \{ (\bar{X}_n - \theta) \sqrt{n} > (2 - \theta) \sqrt{n} \} \\ &\longrightarrow 1, \quad \text{as } n \longrightarrow \infty. \end{aligned}$$

$$\text{Thus } g(T_n) \xrightarrow{P_{\theta_0}} g(\theta_0)$$

Case II : Suppose $\theta_0 < 2$, g is again continuous at θ_0 and

$$g(T_n) \xrightarrow{P_{\theta_0}} g(\theta_0)$$

Case III : $\theta_0 = 2$ Consider

$$\begin{aligned} & P_2 [|g(T_n) - g(2)| > \epsilon] \\ &= P_2 [|g(T_n) - 0| > \epsilon] \\ &= P_2 [g(\bar{X}) > \epsilon] \end{aligned}$$

Let $\epsilon \geq 1$, then $P_2 [g(\bar{X}) > \epsilon] = P(\varphi) = 0$.

Let $0 < \epsilon < 1$, then

$$\begin{aligned} P_2 [g(\bar{X}) > \epsilon] &= P_2 [g(\bar{X}) = 1] \\ &= P_2 \left[\frac{1}{n} \sum_{i=1}^n X_i > 2 \right] \\ &= P_2 \left[\frac{1}{n} \sum_{i=1}^n (X_i - 2) > 0 \right] \\ &= P_2 \left[\sum_{i=1}^n (X_i - 2) > 0 \right] \end{aligned}$$

Hence $\lim_{n \rightarrow \infty} P_2 \left[\sum_{i=1}^n (X_i - 2) > 0 \right]$ will be by dividing both

sides by $2 \cdot \sqrt{n}$

$$\begin{aligned} &\lim_{n \rightarrow \infty} P_2 \left[\frac{1}{2 \cdot \sqrt{n}} \sum_{i=1}^n (X_i - 2) > 0 \right] \\ &= \lim_{n \rightarrow \infty} P_2 \left[\frac{1}{\sqrt{n}} \sum_{i=1}^n \left(\frac{X_i - 2}{2} \right) > 0 \right] = 1/2 \end{aligned}$$

By applying central limit theorem (1.2.5).

Hence $g(T_n)$ is consistent for $g(\theta)$ at all continuity points of g but not at discrete points.

1.3 : JOINT AND MARGINAL CONSISTENCY

1.3.1 : If we are interested in real valued parametric function $g(\theta)$, then definition (1.1.1) will be

$$\lim_{n \rightarrow \infty} P_{\theta, n} [| T_n - g(\theta) | \geq \epsilon] = 0 \quad (1.3.1)$$

that is $T_n \xrightarrow{P_{\theta}} g(\theta), \forall \theta \in \Theta$.

Example : 1.3.1 : Let X_1, X_2, \dots, X_n be i.i.d. r.v.'s with $N(\theta, 1)$ where $\theta = \{ -1, 1 \}$.

Define
$$T_n(C) = \begin{cases} -1 & \bar{X} < C \\ 1 & \text{if } \bar{X} \geq C \end{cases}$$

Note that for $\epsilon > 2, P_{\theta} [| T_n(C) - \theta | \geq \epsilon] = 0$

But for $\epsilon \geq 2,$ we have

$$\begin{aligned} & P_{\theta} [| T_n(C) - \theta | \geq \epsilon] \\ &= P_{\theta} [| T_n(C) - \theta | \geq \epsilon, \bar{X} < C] + P_{\theta} [| T_n(C) - \theta | \geq \epsilon, \bar{X} \geq C] \end{aligned} \quad \dots\dots(1.3.2)$$

Let $\theta = +1$ so (1.3.2) will be

$$\begin{aligned} & P_1 [| -1 - 1 | \geq \epsilon, \bar{X} < C] + P_1 [| 1 - 1 | \geq \epsilon, \bar{X} > C] \\ &= P_1 [2 \geq \epsilon, \bar{X} < C] + P_1 [0 \geq \epsilon, \bar{X} > C] \\ &= P_1 [2 \geq \epsilon, \bar{X} < C] \\ &= P_1 [\bar{X} < C] \\ &= \Phi (\sqrt{n} (C - 1)) \longrightarrow \begin{cases} 1 & \text{if } C > 1 \\ 0.5 & \text{if } C = 1 \\ 0 & \text{if } C < 1 \end{cases} \quad (1.3.3) \end{aligned}$$

as $n \longrightarrow \infty$

Similarly $\theta = -1$

$$P_{\theta} [| T_n(C) - \theta | \geq \epsilon] \longrightarrow \begin{cases} 0 & \text{if } C > -1 \\ 0.5 & \text{if } C = -1 \\ 1 & \text{if } C < -1 \end{cases} \quad (1.3.4)$$

as $n \longrightarrow \infty$.

Hence $T_n(C)$ is consistent for $\theta = -1$ if $C > -1$ and for $\theta = 1$ if $C < 1$

1.3.2 : If we are interested in vector valued parameter that is $\underline{\theta} = (\theta_1, \theta_2, \dots, \theta_k)$ then a vector valued statistic is given by

$T_n = (T_{n1}, T_{n2}, \dots, T_{nk})$. The sequence $\{T_n\}$ is said to be marginally consistent for $\underline{\theta}$ if the i^{th} component of T_n , that is T_{ni} is consistent for the i^{th} component of

$$\theta \text{ (i.e. } \theta_i) \quad \forall i = 1, 2, \dots, K.$$

Example : 1.3.2 : Let X_1, X_2, \dots, X_n be i.i.d. r.v's with

$N(\mu, \sigma^2)$ Here both parameter μ and σ^2 are unknown,

$$\theta = (\mu, \sigma^2).$$

We know that $\bar{X} \longrightarrow \mu$ in probability,

$s^2 = \frac{1}{n} \sum (X_i - \bar{X})^2 \longrightarrow \sigma^2$ in probability so the statistic

$T_n = (\bar{X}, s^2)$ is marginally consistent for

$$\theta = (\mu, \sigma^2)$$

1.3.3 : For any two points $U = (U_1, U_2, \dots, U_k)$ and $V = (V_1, V_2, \dots, V_k)$ in \mathbb{R}^k the Euclidian distance between U and V is given by

$$\|U - V\| = \sqrt{\sum_{i=1}^k (U_i - V_i)^2}$$

consider $K = 1$, then $\|U - V\| = |U_1 - V_1|$

A sequence of T_n is said to be jointly consistent for θ if $\|T_n - \theta\| \longrightarrow 0$ in probability for every $\theta \in \Theta$, that is for every $\epsilon > 0$,

$$P_\theta [\|T_n - \theta\| \geq \epsilon] \longrightarrow 0, \text{ as } n \longrightarrow \infty, \forall \theta \in \Theta \quad (1.3.5)$$

Example : 1.3.3 : Let X_1, X_2, \dots, X_n be i.i.d. r.v.'s with

$N(\mu, \sigma^2)$ both unknown, that is $\theta = (\mu, \sigma^2)$. Here

$T_n = (\bar{X}, s^2)$ is jointly consistent for θ .

Consider $P_\theta [\|T_n - \theta\| \geq \epsilon]$

$$= P [\|(\bar{X}, s^2) - (\mu, \sigma^2)\| \geq \epsilon]$$

$$= P [|\sqrt{(\bar{X} - \mu)^2 + (s^2 - \sigma^2)^2}| \geq \epsilon]$$

$$= P [|(\bar{X} - \mu)^2 + (s^2 - \sigma^2)^2| \geq \epsilon^2]$$

$$\leq P [(\bar{X} - \mu)^2 \geq \frac{\epsilon^2}{2} \text{ or } (s^2 - \sigma^2)^2 \geq \frac{\epsilon^2}{2}]$$

$$= P [\{ (\bar{X} - \mu)^2 \geq \frac{\epsilon^2}{2} \} \cup \{ (s^2 - \sigma^2)^2 \geq \frac{\epsilon^2}{2} \}]$$

$$\begin{aligned} &\leq P \left[(\bar{X} - \mu)^2 \geq \frac{\epsilon^2}{2} \right] + P \left[(s^2 - \sigma^2)^2 \geq \frac{\epsilon^2}{2} \right] \\ &= P \left[(\bar{X} - \mu) \geq \frac{\epsilon}{\sqrt{2}} \right] + P \left[(s^2 - \sigma^2) \geq \frac{\epsilon}{\sqrt{2}} \right] \\ &\longrightarrow 0, \text{ as } n \longrightarrow \infty \end{aligned}$$

As we know that \bar{X} is consistent for μ and s^2 is consistent for σ^2 . Hence (\bar{X}, s^2) is consistent for (μ, σ^2) .

1.3.4 : Joint consistency implies marginal consistency and vice-versa.

This property can be proved as follows:

Suppose that $\{T_n\}$ is jointly consistent for θ . That is

$\forall \epsilon > 0$, and fixed $\theta_0 \equiv \theta$ we have

$$P_{\theta_0} \left\{ \| T_n - \theta_0 \| \geq \epsilon \right\} \longrightarrow 0, \text{ as } n \longrightarrow \infty \quad (1.3.6)$$

Note that $| T_{ni} - \theta_{oi} | \leq \| T_n - \theta_0 \| \quad \forall i = 1, 2, \dots, K$

Hence $P_{\theta_0} \left\{ | T_{ni} - \theta_{oi} | \geq \epsilon \right\} \leq P_{\theta_0} \left\{ \| T_n - \theta_0 \| \geq \epsilon \right\} \longrightarrow 0,$

as $n \longrightarrow \infty$ from (1.3.6)

Thus $T_{ni} \longrightarrow \theta_{oi}$ in P_{θ_0} probability for $i = 1, 2, \dots, K$.

Hence joint consistency implies marginal consistency.

Similarly suppose that $\{T_{ni}\}$ is marginally consistent for θ_i

then for $P_{\theta_i} \left\{ | T_{ni} - \theta_i | \geq \epsilon \right\} \longrightarrow 0,$

as $n \longrightarrow \infty \quad i = 1, 2, \dots, K.$

Note that $P \left[\| T_n - \theta \| \geq \epsilon \right] \leq \sum_{i=1}^k P_{\theta_i} \left\{ | T_{ni} - \theta_i |^2 \geq \frac{\epsilon^2}{k} \right\}$

$\rightarrow 0$, as $n \rightarrow \infty$. Hence the result.

1.4 : UNIFORMLY CONSISTENT ESTIMATOR

1.4.1 : The consistency of T_n for θ implies that, agiven $\epsilon > 0$ and $\delta > 0$ there exist $n_0(\epsilon, \delta, \theta)$ such that

$$P_{\theta} \left\{ | T_n - \theta | < \epsilon \right\} \geq 1 - \delta, \forall n \geq n_0$$

Let $\sup_{\theta \in \Theta} n_0 \left\{ \epsilon, \delta, \theta \right\} = N_0$. If T_n converges uniformly to θ then based on a sample of size $N_0 < \infty$ it is possible to estimate θ so that the probability that the error is at most ϵ is at least $1 - \delta$.

Let X_i be i.i.d. r.v.'s with $N(\theta, 1)$ distribution and define

$$T_n = \bar{X}. \text{ Here observe that for}$$

$$n \geq \left\{ \frac{1}{\epsilon} \Phi^{-1} \left(1 - \frac{\delta}{2} \right) \right\}^2$$

$$P_{\theta} = \left\{ | T_n - \theta | < \epsilon \right\} \geq 1 - \delta, \forall \theta \in \Theta. \text{ That is}$$

$$N_0 = \left\{ \frac{1}{\epsilon} \Phi^{-1} \left(1 - \frac{\delta}{2} \right) \right\}^2 + 1 \quad (\text{say})$$

For $\epsilon = 0.001$ and $\delta = 0.01$ $N_0 = (3330)^2 + 1$.

Similarly consider X_i be i.i.d. r.v.'s with $B(1, \theta)$

distribution and define $T_n = \bar{X}_n$.

By using Normal approximation for large n we observe that for

$$n \geq \left\{ \frac{\sqrt{\theta(1-\theta)}}{\epsilon} \Phi^{-1} \left(1 - \frac{\delta}{2} \right) \right\}^2$$

$$P_{\theta} \left[\left| \bar{X}_n - \theta \right| < \epsilon \right] \geq 1 - \delta, \quad \forall \theta \in \Theta.$$

$$\text{That is } N_0 = \left[\frac{\sqrt{\theta(1-\theta)}}{\epsilon} \Phi^{-1} \left(1 - \frac{\delta}{2} \right) \right]^2 + 1 \quad (\text{say})$$

For $\epsilon = 0.001$ and $\delta = 0.01$

$$N_0 = 66410 + 1.$$

1.5 : ALTERNATIVE DEFINITIONS OF WEAK CONSISTENCY

1.5.1 : If $O_p(n^\alpha)$ is a random variable Z_n such that,

$$\epsilon > 0 \quad \lim_{n \rightarrow \infty} P \left[n^{-\alpha} |Z_n| > \epsilon \right] = 0$$

T_n is said to be weakly consistent for θ , if $T_n = \theta + O_p(1)$

where $O_p(1)$ is a random variable Z such that $\lim_{n \rightarrow \infty} P\{|Z| > \epsilon\} = 0$

Example : 1.5.1 : Let X_1, X_2, \dots, X_n be i.i.d. r.v.'s with

$N(\theta, 1)$. Here \bar{X}_n is consistent estimator for θ and we can

$$\text{write } \bar{X}_n = \theta + (\bar{X}_n - \theta)$$

$$\text{since } \lim_{n \rightarrow \infty} P_{\theta} \left\{ \left| \bar{X}_n - \theta \right| > \epsilon \right\} = 0$$

we have $\bar{X}_n = \theta + O_p(1)$. Hence \bar{X}_n is consistent estimator for θ .

1.5.2 : Let T_n be a statistic based on n i.i.d. observations

adrawn from the $F(x, \theta)$. The estimate T_n has the form

$$T_n = t(F_n(x)), \text{ where } F_n(x) \text{ be the empirical distribution}$$

function and let $t(F(x, \theta)) = \theta$. Then T_n is said to be Fisher consistent for θ . (pp.287 Cox and Hinkley (1979))

Example : 1.5.2 : Sample mean \bar{X}_n is Fisher consistent for population mean. Let θ be the mean of the distribution, then provided estimator $\theta = \int x dF(x)$. Let X_i 's be i.i.d. from $F(\cdot)$.

$$\text{Further } t(F_n(x)) = \int_{-\infty}^{\infty} x \cdot dF_n(x) = \bar{X}_n.$$

We know that from WLLN $\bar{X}_n \xrightarrow{P} \theta$.